

MINAS A5N

MINAS A4A

AINAS A5

AC Servo

Linear Motor Control
 Partner Products



Network Linear Motor Control Servo Catalog

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	AS SOLID ACTUALOU OF A CONC. OF AMULTION ADDE / OF AUG	

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Partners

for RTEX <Slave>

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Ultra High-Speed Network Servo MINAS A5N





*3: For communication period 0.083ms, command update period is 0.166ms only. *4: Slave nodes.

Speed response frequency





4

Maximum pulse frequency



Note: Max, frequency is 4 Mpps when A/B phase feedback scale is used

Drive list

			Motor rated output									
		50 W	100 W	200 W	400 W	750 W	1 k to 1.5 kW	2 kW	3 kW	4 k to 5 kW	7.5 kW	11 k to 15 kW
	Single phase 100 to 120 VAC	A	A	В	С							
		MADH T1105 NA1	MADH T1107 NA1	MBDH T2110 NA1	MCDH T3120 NA1							
P	Single/3-phase 200 to 240 VAC	/	4	A	В	С	D					
ive pov		MA T15 N/	IDH 505 A1	MADH T1507 NA1	MBDH T2510 NA1	MCDH T3520 NA1	MDDH T5540 NA1					
er								E	F	F	G	Н
supply	3-phase 200 to 230 VAC							MEDH T7364 NA1	MFDH TA390 NA1	MFDH TB3A2 NA1	MGDH TC3B4 NA1	MHDH TC3B4 NA1
						D	D	E	F	F	G	Н
	3-phase 380 to 480 VAC					MDDH T2412 NA1	MDDH T3420 NA1	MEDH T4430 NA1	MFDH T5440 NA1	MFDH TA464 NA1	MGDH TB4A2 NA1	MHDH TB4A2 NA1

Upper line: Frame size symbol Lower line: Typical model No.

Note 1: Some motors do not match model numbers in the table. Check correct combination in the A5 series catalog. Note 2: Trailing NA1 in the part number for product with safety I/F option is replaced with N01.

Applicable standards

· UL. cUL • TUV ٠CE

· RoHS





Drive external view



For Panasonic serial data

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Dimensions (mm): W40 × H150 × D135 (A-frame)

MINAS A4N

For a controller not compatible with A5N



Note: Realtime Express and RTEX are registered trademark of Panasonic Corporation Realtime Express is a high speed synchronous motion network developed by Panasonic Corporation.

RTEX partner products

		Ма	ster		Slave				
Partner	PCI	USB	Stand- alone	PLC	Digital I/O	Analog I/O	Pulse output	Stepper drive	Gateway
AJINEXTEK CO., LTD.									
Anywire Corporation									
Asahi Engineering Co., Ltd.			•						
Aurotek Corporation	•				•				
Shanghai Bitpass Automation Technology Development Co.,Ltd.	•								
HI-P Tech Corporation									
Panasonic Electric Works SUNX Co., Ltd.									
Delta Tau Data Systems, Inc.									
Prime Motion Inc.									
SOFT SERVO SYSTEMS, INC.									
TIETECH Co.,Ltd.	•								
Trio Motion Technology Ltd.			•						

Communication ASIC MNM1221

For developing RTEX product, this ASIC is necessary. (See note)



	Specification
Part No. for ordering	DV0P444-9
Packing quantities	90
Power supply voltage	3.3 V
Current consumption	Max. approx. 100 mA (for reference)
Operating ambient temperature	–40 to +85°C
Package	LQFP100pin 14 × 14 mm Lead pitch 0.5 mm
RoHS	Compliant
Operation mode	Master/slave

Note: As long as the target is noncompetitive to Panasonic products. For disclosure of technical data, nondisclosure agreement (NDA) is required. For details, consult us.



RTEX <Master>

RTEX Master Board

▶ Features

- RTEX network Master Board
- Network Speed 100 Mbps, Communication Period 0.5 ms
- Support RTEX Standard Servo Profile, Standard I/O Profile
- Basic configuration is 16 axes control
- (Can be expanded to 20,24,28, and 32 axes)
- Easy to wire, saving wiring working-hour
- Max. 32 nodes
- Network connection 100 BASE-TX, STP Cable (above CAT5e)
- Excellent Error correction
- Multi-axes linear / circular interpolation
- Limit setting functions soft stop, emergency stop, and two positions

Specification

Item	Description				
RTEX Master Board					
Max. number of nodes	32				
Max. ring loop length	200 meters				
Max. node to node length	60 meters				
Connector / cable type	RJ45 RX/TX, STP (Shielding type)				
Power supply / current consumption	5 VDC / 1.0 A				
Position range	32 bits (±2,147,483,648)				
Motion					
Interpolation	Max. 32 synchronized drive, 2 to 4 axes linear interpolation, and 2axes arc interpolation,				
Gantry motion	Max. 32 slave axes can follow the master axis to move synchronously				
Position compare signal	All servo axis, up to 1 kHz				
Software					
User Agent Software	EzSoftware RM				
Operating System	Windows XP (32 bit, 64 bit), Windows 2000				
General specification					
Dimension	174.63 × 106.00 mm				
Weight	120 g (Expend 32axes-161 g)				
Operation temperature	0°C to 60°C				

Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, Dalseo-gu, Daegu-city, Korea TEL: +82-593-3700 FAX: +82-593-3703 URL: www.ajinextek.com E-mail: marketing@ajinextek.com



PLC Direct Access RTEX Motion Controller PI-2 00

Features

Building a leading edge high speed motion network at low cost under PLC

Direct PLC access

- The controller runs the motion program installed in PI while accessing PLC data register.
- · Preparation of ladder program for communication is not required on PLC.
- · No CPU burden on PLC.

Simple motion control through data register

- Motor can be controlled by operating PLC data register.
- · Multiaxial motor can be controlled/monitored by simply operating numeric values on the data register.
- · PLC operator having no knowledge on communication of motion (RTEX) can control the motor.

Stepping motor can be mixed

- · The motion network can contain servo motor and stepping motor.
- · Ultra high-speed fully-synchronized motion system can be built.



(3) The PI writes status information of each axis to data register.

Specification

Item	Description	
Power supply	24 VDC 10 300 mA MAX	
Operating temperature and humidity	0 to 50°C, 90 RH max. (no dewing)	
Outline dimensions mm	W24.5 × D105 × H160	
Communication with PLC	Ethernet 10/100 BASE-T Conforms to MC protocol	
Setting tool	PIAssistance (complimentary)	
Control signal I/O	Initialization input, system alarm output and node alarm output	
Motion network	RTEX command updating period: 1 ms	
No. of connection nodes	Max. 16	
Motion control	Positioning and synchronized operation	

Contact to: Asahi Engineering Co., Ltd. Kodaira Works

3-3-22, Gakuen-Higashicho, Kodaira-shi, Tokyo 187-0043, Japan TEL: +81-42-342-4422 FAX: +81-42-342-4423

URL: http://www.asahi-engineering.co.jp/ E-mail: ae-sales@asahi-engineering.co.jp

Manufacturer/ Aurotek Corporation

RTEX Network Motion Control board MCN-02P

Features

- RTEX (Real Time Express) servo network
- Network Speed 100 Mbps, communication period 0.5ms
- Easy to wire, saving wiring working-hour
- Up to 32 nodes
- Excellent error correction
- Multi-axis linear / circular interpolation
- Multi-axis synchronous motion (for gentry)
- Up to 16 boards in one PC



Specification

Item	Description				
RTEX motion control					
Module type support	Servo motor drive, Linear motor drive, Stepper drive, I/ module, Pulse module				
Max. number of nodes	32 (MCN-8032P)				
Max. ring loop length	200 meters				
Max. node to node length	60 meters				
Connector / cable type	RJ45 8 pins, STP (Shielding type)				
Isolation voltage	1500 Vrms				
Noise immunity	ver 2.5 KV				
LED loop status	Link / Comm (two elements LED)				
Position range	32 bits (±2,147,483,648)				
Motion					
Interpolation	polation 32-axes linear interpolation / 2-axes circular interpolation (max. 16 pairs 2-axes circulator interpolation)				
Gantry motion	Max. 31 slave axes can follow the master axis to move synchronously				
Position compare signal	All servo axis, up to 1 kHz				
Software					
Software utility	MCN80XXP series utility for motion test and diagnosis				
Drive/LIB	Drive for Windows XP, DLL function for windows applications				
General specification					
Certification	CE (applying)				
Dimension LxWxH	175 × 100 × 20 mm				
Power consumption	5 V @ 500 mA				
Operation temperature	0°C to 60°C				

Contact to: Aurotek Corporation

1st. Floor No. 60, Jhou- ih St. Nei-Hu District, Taipei 114, Taiwan TEL: +886-2-6600-7574 FAX: +886-2-8752-3347

RTEX <Master>

URL: www.robot.com.tw

E-mail: sales@robot.com.tw



RTEX <Master>

D-

Turbo PMAC2 Realtime Express Controller Turbo-PMAC2-RTEX series

Features

High specification motion controller with built-in PLC

- Stand alone specification with built-in high-speed DSP max. 240 MH Provided with USB 2.0. Ethernet or RS232C as standard port to communicate with host PC. Memory sharing with DPRAM option is possible.
- Advanced tra ectory calculations such as inverse kinematics and look ahead

Advanced trajectory calculations necessary for linear interpolation, arc interpolation and spline interpolation, and robot control, and CP control by micro line segment feed are provided as standard features. All Turbo PMAC functions such as 2D and 3D positional compensation are available.

- Various field networks promote multivendor environment (option) By adding CC-Link/DeviceNet/Profibus communication module, different manufacturers devices can be connected.
- I/O, pulse I/O, A/D and D/A function without intervention of network To standard accessories such as universal I/, pulse input and pulse output, optional A/D and D/A can be added. By using the remote I/ unit ACC-34AA, expansion of 32 inputs, 32 outputs and universal I/ are possible.

Because these can directly access the memory without intervention of a network, they can be easily handled.

Specification

	Hardware specification	Software specification		
Item	Description	Item	Description	
Processor	DSP56300 series (Freescale)	No. of control axes	Max. 32 axes/16 coordinate systems	
	Standard 80 MHz (option 240 MHz)	Controlling method	PTP control, trajectory (CP) control	
Memory	Built-in 128 K × 24-bit SDRAM (option 512 K × 24-bit)	Interpolation	2-axis to 9-axis linear interpolation, 2-axis arc interpolation (rotable) 3-axis	
Backup	Settings and program can be stored to Flash		spiral interpolation, spline interpolation	
Duonup	RAM.	Unit of control	Pulse, or other desired industrial metrological unit	
Communication interface	USB 2.0/Ethernet 100 BASE-TX (concurrent use is not possible), RS232C	Accelerating/ decelerating	Trapezoid/ S-curve ptional acceleration/ deceleration pattern (PVT mode)	
Power supply	24 VDC 900 mA Min.	Accelerating/	Min 1 ms	
Pulse input	A/B phase rectangular input × 1-ch (6 MHz before multiplied by 4)	decelerating time Positioning range	2 ³⁵ counts	
Pulse output	Pulse/direction output × 1-ch (max. 1.31 MHz)	Position compensation	Ball screw pitch error correction, orthogonal axis correction, plane correction	
Universal I/O	Input 8 points, output 4 points (sink/source selectable) Remote I/ expandable (ACC-	Other correcting functions	Backlash compensation, tool diameter compensation	
	34AA)	PLC function	Interpreter/compile type total: 64 programs	
Universal A/D	12-bit × 2-ch (option)	Synchronous control	Electronic gear, electronic cam, motion synchronous I/ output (synchronous M variable)	
Universal D/A	10 V 12-bit × 1-ch (option)	Advanced tra ectory calculation	Look ahead, forward/inverse kinematics operation	

Contact to: Delta Tau Data Systems, Inc. USA West Coast Headquarters

21314 Lassen Street Chatsworth, CA 91311, United States TEL: +1-818-998-2095 FAX: +1-818-998-7807

RTEX <Master>

Motion Master Control Board HCRTEXsd -PCI

Features

Motion of up to 2 axes nodes can be controlled from the single board.

The board can control up to 32 nodes of axes and peripheral devices.

- Simple sequence function reduces the load on host PC.
- Parameters and status of servo drive and motor can be uniformly managed from the host.

Parameter setting and changing of servo drive (MINAS-A5N), various monitoring (alarm, limit signal, etc.), diagnosis of condition and troubleshooting can be easily performed.





Flexible expandability by expanding peripheral lineup

In addition to control of MINAS-A5N, system can be extended to the desired degree by making use of peripheral boards (DI/D board, Stepper drive board and pulse output board).



Full software control

Specification

Speed (linear, S-curve acceleration/deceleration) and trajectory (linear and arc interpolation) are fully controlled by software, precisely at a low cost.

For typical system configuration, see p. 28.

	Item	Description				
	Part number	HCRTEXsd	HCRTEXsd-PCI			
Воа	Host interface	USB2.0 Highspeed (480 Mbps)	PC15V/3.3V signal environment compatible (PCI Spec2.1 Target)			
rd spe	Power supply	24 VDC 15 300 mA MAX	+3.3 VDC, 0.96 A (TYP) +5 VDC, 0.2 A (TYP)			
eifica	Operating temperature and humidity	0 to 50°C, 85%R⊦	H max. (no dewing)			
tion	Outline dimensions mm	W130 × D150 × H30	W167.64 × D64.41 (PCB only) 1 slot, LowProfile compatible			
	No. of control nodes	3	2			
В	Motion control	Positioning con	trol by software			
ard function	Motion function	Positioning, linear and arc (continuous) Linear, S-curve acceleration/deceleration (triangle driving avoidance function) Software accurately maintains arc circumferential velocity constant Simple sequence function Setting and reading of servo drive (MINAS-A5N) parameters Other motion functions				

Contact to: HI-P Tech Corporation Sales Dept.

1-27-23, Higashitokoroz	zawa, Tokorozawa-shi, S	Saitama 359-0021, Japan
TEL:+81-4-2951-5381	FAX:+81-4-2951-5383	URL: http://www.hptec.co.jp



HCRTEXsd-PCI

RTEX

<Maste

URL: http://www.deltatau.com

E-mail: sales@deltatau.com

RTEX <Master>

PLC Positioning Unit RTEX AFPG4 610, etc.

Features

- Compact PLC is easier to operate to control network servo MINAS A4N/A5N. (Units of Ver.1.3 or later will support A5N.)
- High speed 100 Mbps communications enable high precision arc/linear/spiral interpolation.
- 2-axis, 4-axis and 8-axis units are lined up and can be used to configure system of up to 16 axes with FP Σ and 256 axes with FP2SH.
- User-friendly tool software [Configurator PM] provides strong support for setup, start and monitor.
- Max. No. of position command points is 600/axis and max. position command rate is 32 Mpps, assuring margin of performance.
- Manual pulser input is provided to enable fine teaching.





Specification

Part	No. (FPΣ/FP2SH)	AFPG4 610/AFP24 610	AFPG4 620/AFP24 620	AFPG4 6 0/AFP24 6 0					
No. of co	ntrol axes	2-axis (2 axes × 1 system)	2-axis (2 axes × 1 system) 4-axis (4 axes × 1 system) 8-axis (8 axes						
	Control method	P	PTP control, trajectory (CP) control						
	Interpolation control	2-axis, 3-axis linear interp	2-axis, 3-axis linear interpolation, 2-axis arc interpolation, 3-axis spiral interpolation						
	Control unit		pulse/ µm/ inch/ degree						
Desition	Positioning data		600 points/axis						
control	Backup	Paramete	r and data table can be stored	to FR M.					
function	Accelerating/ decelerating method	Linear acceleration/	Linear acceleration/deceleration and S-curve acceleration/deceleration						
	Accelerating/ decelerating time	0 to 10,000 ms (in unit of 1 ms)							
	Positioning range	Signed 32-bit (-1,073,741,823 to 1,073,741,823 pulses) increment, absolute designation							
Velocity of	control function	With JOG operation (infinite feed operation)							
Torque co	ontrol function	W	/ith real time torque limit functi	on					
Origin	Searching method	Near home (D)	search, limit search, phase	search, hit and stop					
return	Creep velocity		Setting is optional						
Other		Pulser input operation/ auxiliary output code, auxiliary output contact/ dwell time/ in position contact/ 2-axis synchronization operation							

MINAS A4N and A5N cannot be mixed in a system.

Contact to: Panasonic Electric Works SUNX Co., Ltd.

2431-1, Ushiyama-cho, Kasugai, Aichi 486-0901, Japan URL: http://panasonic-electric-works.net/sunx



RTEX

Multi PLC Direct Connection 16-axis Motion Controller InterMotion Series JOY-AMXR-P, etc.

Features

- Directly connectable to Mitsubishi Electric PLC (CPU with Ethernet: e.g. Q03UDECPU) References CPU D register according to MC protocol.
- Directly connectable to MR N PLC (CPU with Ethernet: e.g. CJ1M-CPU11-ETN)
- Directly connectable to Keyence PLC KV-5000
- Internal control program of [InterMotion] can be developed in the machine control script language [MOS language].

Motion, $\ensuremath{\mathsf{I}}/$, communication and sequence can be controlled.

• 1 ms scan D UT interlocked trajectory control (coating valve control, spray valve control, etc.) is possible.



Specification

Item	Description
No. of control axes	For max. 8 axes, 10 Mpps pulse train position command can be used as necessary. (Low cost version is available: RTEX axis only without pulse train output)
Controlling method	Each axis is independent PTP. Max. 8 axes sync PTP. Linear interpolation, 2-axis arc interpolation, 3-axis spiral interpolation, 32-bit length. 1 ms scan D UT interlocked trajectory control option (coating valve control, spray valve control)
Internal control program development	Control program can be developed by using the C-like multiprocessing machine control language M S language]. Motion, I, communication and sequence can be controlled. As the development environment, M S Bench AM] is required.
Accessory IO	±CW, ±CCW pulse output, ±A, ±B, ±Z input. Servo on, reset output. ±OT, alarm input, for 8 axes. Universal IN 8 points. Universal OUT 8 points. Non-insulated RS232 1 ch, Insulated RS485 1 ch. (By adding remote I , 192 IN and 192 UT are available.)
Host controller	Mitsubishi Electric PLC with CPU with Ethernet (reference CPU D register) Keyence PLC KV-5000 (reference data memory) MR N PLC with CPU with Ethernet (reference data memory) r, Windows PC with Ethernet (DLL for XP supplied)

Contact to: **Prime Motion Inc.** (InterMotion - Special site: http://www.intermotion.jp) 1134-12, Akaho, Komagane-shi, Nagano, 399-4117, Japan

TEL:+81-265-82-2990 FAX:+81-265-82-2292 URL: http://www.primemotion.com/

1

Manufacturer/ Bitpass Shanghai Bitpass Automation Distributor: Lagada & Refut Zana Agent Co., Ltd.

RTEX <Master>

RTEX motion controller Board JES-PCI 2N

Features

- Real-time communication based on 100BASE-TX
- 0.5ms cycle with up to 32 axes
- High-speed DSP, FP A as a master device
- Complex multi-card support up to 4 cards, the maximum control 128-Axis (customizable)
- Acceleration and deceleration control mode:
- T-shaped, S-shaped, trigonometric-shaped
- High-speed position capture by hardware interrupt
- Synchronous control mode



Specification

	Item	Description
	Number of control-Axis	32
z	DSP LSI	TMS320F28335PGFA (Texas Instruments)
lotor	Control Mode	Command mode
contr	Drive Function	Linear interpolation, Circular interpolation
<u> </u>	Other function	Virtual axis, Axis overlay, Master-Slave, Position Capture, Non-linear error compensation, Electronic gear, Electronic cam
	Acc-Dec Mode	T-shaped, S-shaped, trigonometric-shaped
5	Input	48 (24 VDC±10%)
0	Output	32 (24 VDC 10)
NetWork RealtimeExpress (RTEX)		RealtimeExpress (RTEX)
munic	Communication speed	100 Mbps
ation	Physical Layer	100 BASE-TX full duplex (by IEEE 802.3u)

Contact to: Shanghai Bitpass Automation Technology Development Co., Ltd. floor1601 jinyi Mansion.441He Nan N.Rd, Shanghai, China TEL: +86-21-63570803 FAX: +86-21-63570802 URL: http://www.shhuitong.net

Manufacturer/ Soft Servo SYSTEMS, INC.

Universal motion controller

SMP series

Features

Full software motion controller

- Windows real time extension enables high performance software control from PC
- Hardware saving and cost saving with full software motion control
- Can be flexibly used to meet various control specifications and applications with wide variety of functions including NC Multisystem independent control function divides 32 axes into up to 32 systems

Machine elements such as electronic cam, electronic gear and electronic clutch can be defined and virtually operated

NET compatible

Real time API can also be used for flexible application development





• PLC (ladder control) can be used with accompanying LadderWorks PLC

Specification

		SMP4 0	SMP 0	SMP1600	SMP 200	
Max. No. of control axes		4	8	16	32	
Max. No. of interpolation	Linear interpolation	4	8	16	32	
control axes	Arc interpolation		Simultaneous	2-axis (helical)		
Acceleration/deceleration profile		Can be indivi je	idual set by using li erk control and mo	inear, bell, expone tion profile functior	ntial function, 1.	
No. of full synchroni ation	control gantry combinations	2	4	8	16	
Max. No. of PLC axes		4	8	16	32	
Interpolation period		1 ms (with 0.	5 ms option)			
Linear axis		99999	9.999999999 mm,	99999.99999999	199 inch	
Max. command value	Rotation axis	999999.99999999 deg				
Min potting unit	Linear axis	0.000000001 mm, 0.0000000001 inch				
Min. setting unit	Rotation axis	0.00000001deg				
Deserved an ending	Execution of G code file	0	0	(up to 8 axes)	(up to 8 axes)	
Programmed operation	Functional computation and conditional branch	0	0	(up to 8 axes)	(up to 8 axes)	
User motion profile (with b	uffer function)	Continuous 500 steps				
Ma or tra ectory control functions		Automatic corner deceleration, corner in position, automatic arc speed limit, high accuracy contour look ahead control				
I/O control	Control period		5 r	ns		
By LadderWorks PLC	Max. No. of steps		100	000		
By Lauder WORKS PLC	Max. No. of control points	I: 4000 / : 4000				

Contact to: SOFT SERVO SYSTEMS, INC.

272-1 Norieda-cho, Minami-ku Hamamatsu, Shizuoka 432-8053, Japan TEL: +81-53-444-5771 FAX: +81-53-444-5773 URL: http://www.softservo.co.jp/





RTEX <Master>

PCI Motion Control Board

16 002-MBP-LE01/01, etc.

Features

Motion control board best suited to build motion control system

- 2 axes synchronous control
- Servo control of 32 axes in 1 ms period for various applications.
- Wide array of external interfaces
 - Because the board is provided with such external interfaces as RS485 communication, 2 external inputs (24 V compatible) and 1 external output, it can be connected to various devices.



Specification

	Series list				
Model	No. of control axes	Built-in pulse train conversion software	Built-in PLC		
169002-MBP-LE01/01	32	-	-		
169002-MBP-LE01/02	32	0	-		
169002-MBP-LE01/11	16	-	-		
169002-MBP-LE01/12	16	0	-		
169002-MBP-LE01/21	8	-	-		
169002-MBP-LE01/22	8	0	-		
169002-MBP-LE01/23	8	-	0		

Item		Description	Remarks
	CPU	SH4 HD6417750R 200 MHz	
Architecture Memory		FLASH ROM 8 MB SDRAM 16 MB SRAM 128 KB EEPROM 8 KB Shared memory 128 KB	with backup function For data transfer
Come interfece	Connector	RJ-45 × 2	
Servo Internace	Interface	Compatible with MINAS A4N/A5N series	
External input		2 P RT (with sink/source switching)	
External output		1 P RT (with sink/source switching)	
Remote I/O		CUnet	
Serial interface	Interface	RS-485	MK 40 (Step Technica Co., Ltd.)
specification	Transmission rate	115.2 Kbps (Max.)	
Compatible OS		Microsoft Windows XP	If you use a different S, consult us.

Contact to: TIETECH Co.,Ltd.

 1-3-4 Shioya-cho, Minami-ku, Nagoya 457-0078, Japan

 TEL: +81-52-824-7375
 FAX: +81-52-811-4737

 URL: http://www.tietech.co.jp/





<Master>

PLC Motion Unit

B 6 2101-UNT-LE02

Features

PLC motion unit best suited to build motion control system

• 2 axes synchronous control

All servos sync to the host device assuring precise CP control. Communication period is 1 ms over max. 32 axes allowing various control settings.

Software interface easily transportable from pulse train type software

Command functions such as single axis PTP control, linear interpolation, arc interpolation, origin return and drive parameter change are provided. The unit will operate as the host controller sets the parameters and calls DLL functions. (DLL functions will be disclosed.)





Yokogawa Electric e-RT 2.0 series PLC compatible

Connection of Yokogawa PLC to Panasonic network servo By connecting the unit to the host PLC via PCI bus and to the driving section via network interface, various monitoring operations can be performed without stress. The combination of the unit and PLC expands functions such as to



external signal interface.> Specification

Specification		Item		Description		Remarks
Max. No. of control axes	32	СРИ		SH4 7750 200 MHz (Renesas) Peripheral clock 50 MHz		
Positioning data quantity	No limit		DOM	Flash R M	8 Mbyte	
Computing	1.0 mo	Memory	ROM	EEPR M	8 Kbyte	
period	1.0 ms		RAM	SDRAM	8 Mbyte	
PLC connection	PCI			DPRAM	256 Kbyte	
Interface to			PCI hus	Bus width	32-bit	
servo drive	RTEX 100 Mbps	Bus interface Clo		Clock	33 MHz PCI Rev.2.3 compatible	
Continuous	MINAS A4N/A5N series	Internal		Main power supply	5 V/ 3.3 V	
	Assorting to heat DLC	Power power CF	CPU power supply	3.3 V, 1.5 V		
input	specification ¹	Suppry	supply	FP A	3.3 V, 2.5 V, 1.2 V	
External signal	According to host PLC	Watchdog function	WDT	Watching time	1.6 s	
Manual signal	According to host PLC	Monitor	LED	2 points	RUN reen	Blinks during operation
pulser interface	specification '				LINK reen	
Various	High-speed data	Communication	RS2 2C	1-ch		
monitoring	processing via PCI bus	communication	RTEX	1-ch		
Interpolation	Linear, arc, continuous, multiplex, helical pressure control ¹	Setup DIPSW		Universal input For JTA .ICE conne For FP A setting	4 ection 1 2	
*1 May be separate	ly defined.	OS		VxWorks6.4		

Contact to: TIETECH Co.,Ltd.

1-3-4 Shioya-cho, Minami-ku, Nagoya 457-0078, Japan TEL: +81-52-824-7375 FAX: +81-52-811-4737

URL: http://www.tietech.co.jp/

RTEX <Master>

Motion Coordinator and RTEX Interface Module Motion Coordinator MC464 / Panasonic RTEX Interface Module

Features

- Supports digital drive systems up to 64 axes using multiple RTEX
- Based on 64bit 400MHz MIPS processor
- Anybus-CC Module support allowing flexible factory communication options
- High accuracy double floating point / 64 bit integer resolution
- Multi-tasking BASIC programming
- IEC 61131-3 programming support
- Backlit LCD display
- Ethernet programming interface
- Expansion flexibility with clip on modules allowing quick interchangeability
- Built-in Ethernet-IP connectivity

Specification

	Item	Description	Item	Descriptio
MC46	54		Panasonic RTEX I	nterface Module
S ⊒	Axes Controlled	Up to 64		Ethernet based N
yste	RTEX Drive Networks	Up to 7	Network	A4N / A5N
lity m	Built-in Synchronization Encoder Input	es		100Mbps 1msec
	Multi-Tasking TrioBASIC	es	Network Speed	or 500usec updat
	Number of Simultaneous Programs	30		operation
-0	Motion Perfect Windows Software	es	Topology	Ring
rog	Stand-Alone operation	es	Max Slaves	
gra	Permanent Flash EPR M for program storage	es	per Interface Ring	32
m	Available memory for user programs	8MByte	Max Interfaces	
nin	User table memory	512,000	per MC464	7
ů.	Accurate and fast real number mathematics	64 Bit Int / Double Floats	Max Axes ner	
	Program Trace Debugger	es	MC464	64
	Named Constants and variables	es	Bus to MC464	32 Bit
Z	Linear, Circular, Helical, Spherical Interpolation	es	Dus to MC404	
otic	Cams, earbox, Clutches	es	Registration Inputs	8 × 24 V Inputs +
ň	64 bit position storage	es		
Ę	Acceleration/Deceleration S-Ramp Controls	es	ptically isolated	
ncti	5 Term Control	es	registration inputs	
on	Max Interpolated Axes	64, Multiple groups	Map Any I/ to	
0	Hardware Position Capture (Registration)	1us	Any Axis	
	Ethernet port	10/100 Base-T	Supported Modes	Cyclic Position, C
	RS232 Serial Port	128kbits/sec		Speed, Cyclic Tor
	RS485 Multi-Drop	es		
	Ethernet IP	es		
Inte	Modbus TCP	es		
erfe	Anybus Module	es		
lce	pto-Isolated Inputs	16		
s	pto-isolated utputs with current limit	8		
	Max Input / utput Expansion Channels	512		
	CAN Analogue Inputs Capability	es		
	Real Time Clock	es Des recents and data		
		Programs and data		
ack		DIN Hall / Panel Mount		
agir	Module size (H × W × D)	201 × 155 × 56 mm		
b D	UL and CE marked for EMC	es		

Network	Ethernet based MINAS A4N / A5N
Network Speed	100Mbps 1msec or 500usec update operation
Topology	Ring
Max Slaves per Interface Ring	32
Max Interfaces per MC464	7
Max Axes per MC464	64
Bus to MC464	32 Bit
Registration Inputs	8 × 24V Inputs + 1 Drive Registration Input/Axis
ptically Isolated registration Inputs	
Map Any I/ to Any Axis	
Supported Modes	Cyclic Position, Cyclic Speed, Cyclic Torque

Contact to:	Trio	Motion	Technology Ltd.	
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Shannon Way, Tewkesbury, Gloucestershire, GL20 8ND, United Kingdom TEL: +44-1684-292333 FAX: +44-1684-297929 URL: http://www.triomotion.com

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MEMO

Manufacturer/ AJINEXTEK A JINEXTEK CO., LTD.



Motion Function Module RTEX-PM

Features

- Single axis (selectable from two(2) to four(4) axes) slave motion function extension module for RTEX
- Max 32 modules can be mounted on the PCI-Rxx04 board
- Synchronizing start/stop function for each node
- Digital control input / output for servo control
- Motion control signal input/output
- Sensor input and universal digital input/output function



Specification

Item	Description
RTEX-PM	
Module function	RTEX based 1axis of slave motion function module
NODE ID setting	Decimal number rotary switch x 2 (0 to 31)
Mounting Method	Standard 35 mm DIN rail mounting
Power supply / current consumption	24 VDC / 200 mA (Connected to TB1 outside the module, without external I/ power)
LED display	Power (ellow), Live (reen), Error (Red), Com (ellow)
Pulse output	PULSE+, PULSE–, DIR+, DIR– LINE TRANSMITTER (5 VDC, MAX. 13MPPS)
Encoder input	ENC-A, /A, B, /B, Z, /Z : High-speed Photo-coupler (5 VDC, MAX. 8 MPPS) ENCPWR, D ND : 5 VDC output (when using the encoder for step motors)
Motion control Input / Output	ALARM, INP, RD (IN4) : Photo-coupler (24 VDC Level) SV N, ALMC, DCC, TR (): Dalington Photo-coupler (24 VDC Level) LIMIT+, LIMIT-, ORG : Photo-coupler (24 VDC Level) TRG+, TRG- : Line Transmitter (5 VDC Level) BRK (OUT4) : Photo-coupler + Drive IC (24 VDC Level) PC M, NC M: Digital I/ Positive and Negative Common Motion Connector : Honda 26 pin X 1 EA Motion I/ Connector : 3M 26 pin X 1 EA
Universal input	IN2, IN3 : Photo-coupler (24 VDC Level)
Universal output	OUT2, OUT3 : Photo-coupler + Drive IC (24 VDC Level)
Software	
User Agent Software	EzSoftware RM
Operating System	Windows XP (32bit, 64bit), Windows 2000
General specification	
Dimension H D W	120 × 110 × 25 mm
Weight	192 g
Operation temperature	0°C to 60°C

Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, Dalseo-gu, Daegu-city, Korea TEL: +82-593-3700 FAX: +82-593-3703

URL: www.ajinextek.com E-mail: marketing@ajinextek.com

RTEX <Slave>

Digital Input/Output Function Module RTEX-DB 2T

Features

- Slave digital input/output function extension module for RTEX Used by connecting to PCI-R1604 - RTEX communication master board
- Max 32 slave modules can be connected (node ID setting is required)
- 16 channels digital input control (Above Min 2 mA / channel, 24V level)
- 16 channels digital output control (below max 50 mA / channel, 24V) level)
- Caution must be taken in system configuration to limit the maximum Current to 800 mA (50 mA / channel * 16 channels) when all 16 channels are used



Specification

Item	Description		
RTEX-DB 2T			
Module function	RTEX based slave 16ch digital input 16ch digital output function module		
NODE ID setting	Decimal number rotary switch × 2 (0 to 31)		
Mounting Method	Standard 35 mm DIN rail mounting		
Power supply / current consumption	24 VDC / Max. 500 mA (TB1 Connection to utside Module)		
LED display	Power (ellow), Live (reen), Error (Red), Com (ellow) IN1 to IN16 (ellow) UT1 to UT16 (Red)		
Digital input/output	32 channels, 24 VDC Level (16ch Input / 16ch utput) IN1 to IN16 : Photo-coupler isolation (More over MIN. 2 mA/ch) UT1 to UT16 : Photo-coupler isolation (Below MAX. 50 mA/channel) PC M, NC M : Digital I/ Positive and Negative Common Connector : Phoenix 16 X 2 (MCD 1.5/16-GIF-3.81)		
Software			
User Agent Software	EzSoftware RM		
Operating System	Windows XP (32bit, 64bit), Windows 2000		
General specification			
Dimension H D W	100 × 90 × 40 mm		
Weight	245 g		
Operation temperature	0°C to 60°C		

Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, Dalseo-gu, Daegu-city, Korea TEL: +82-593-3700 FAX: +82-593-3703

URL: www.ajinextek.com E-mail: marketing@ajinextek.com



RTEX <Slave>

Digital Input Function Module RTEX-DI 2

Features

- Slave digital input function extension module for RTEX
- Used by connecting to PCI-R1604 RTEX communication master board
- Max 32 slave modules can be connected (node ID setting is required)
- 32 channels digital input control (Above Min 2 mA / channel, 24V level)



Manufacturer/ AJINEXTEK ANT AJINEXTEK CO., LTD.

RTEX <Slave>

Digital Output Function Module RTEX-DO 2T

Features

- Slave digital output function extension module for RTEX
- Used by connecting to PCI-R1604 RTEX communication master board
 Max 32 slave modules can be connected (node ID setting is required)
- 32 channels digital output control (below max 50 mA / channel, 24 V level)
- Caution must be taken in system configuration to limit the maximum current to 1600 mA (50 mA / channel 32 channels) when all 32 channels are used



Specification

Item	Description					
RTEX-DO 2T						
Module function	RTEX based slave 32ch digital output function module					
NODE ID setting	Decimal number rotary switch × 2 (0 to 31)					
Mounting Method	Standard 35 mm DIN rail mounting					
Power supply / current consumption	24 VDC / Max. 500 mA (TB1 Connection to utside Module)					
LED display Power (ellow), Live (reen), Error (Red), Com (ellow) UT1 to UT32 (Red)						
Digital input	utput 32 channels, 24 VDC Level UT1 to UT32 : Photo-coupler isolation (Below MAX. 50 mA/channel) PC M, NC M : Digital I/ Positive and Negative Common Connector : Phoenix 16 X 2 (MCD 1,5/16-GIF-3,81)					
Software						
User Agent Software	EzSoftware RM					
Operating System	Windows XP (32bit, 64bit), Windows 2000					
General specification						
Dimension H D W 100 × 90 × 40 mm						
Weight	245 g					
Operation temperature	ion temperature 0°C to 60°C					

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Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, D	alseo-gu, Daegu-city, Korea
TEL: +82-593-3700	FAX: +82-593-3703

URL: www.ajinextek.com E-mail: marketing@ajinextek.com

Specification

Item	Description				
RTEX-DI 2					
Module function	RTEX based slave 32ch digital input function module				
NODE ID setting	Decimal number rotary switch × 2 (0 to 31)				
Mounting Method	Standard 35 mm DIN rail mounting				
Power supply / current consumption	24 VDC / Max. 500 mA (TB1 Connection to utside Module)				
LED display	Power (ellow), Live (reen), Error (Red), Com (ellow) IN1 to IN32 (ellow)				
Digital input	Input 32 channels, 24 VDC Level IN1 to IN32 : Photo-coupler isolation (More over MIN. 2 mA/ch) PC M, NC M : Digital I/ Positive and Negative Common Connector : Phoenix 16 X 2 (MCD 1,5/16-GIF-3,81)				
Software					
User Agent Software	EzSoftware RM				
Operating System	Windows XP (32bit, 64bit), Windows 2000				
General specification					
Dimension H D W	100 × 90 × 40 mm				
Weight	245 g				
Operation temperature	ature 0°C to 60°C				

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Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, Dalseo-gu, Daegu-city, Korea TEL: +82-593-3700 FAX: +82-593-3703 URL: www.ajinextek.com E-mail: marketing@ajinextek.com RTEX <Slave>



RTEX <Slave>

Analog Input Function Module RTEX-AI H

Features

- Slave Analog input function extension module for RTEX
- Used by connecting to PCI-R1604 RTEX communication master board
- Max 32 slave modules can be connected (node ID setting is required)
- 8 channels analog input control



► Specification

Item	Description					
RTEX-AI H						
Module function	RTEX based slave 8ch analog input function module					
NODE ID setting	Decimal number rotary switch × 2 (0 to 31)					
Mounting Method	Standard 35 mm DIN rail mounting					
Power supply / current consumption	24 VDC / Max. 500 mA (TB1 Connection to utside Module)					
LED display	Power (ellow), Live (reen), Error (Red), Com (ellow)					
Number of input channels	8 channels					
Resolution	16 bit					
Analog input	Input 8 channel Voltage mode: -10V to +10V, Electric current mode : 4 to 20 mA (control the switch) Resolution: 16 Bit Sampling speed: 100 KHz Connector: Phoenix 10 X 2 (MCD 1,5/20-G1F-3,81)					
Software						
User Agent Software	EzSoftware RM					
Operating System	Windows XP (32bit, 64bit), Windows 2000					
General specification						
Dimension H D W	100 × 90 × 40 mm					
Weight 244 g						
Operation temperature 0°C to 60°C						

Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, Dalseo-gu, Daegu-city, Korea TEL: +82-593-3700 FAX: +82-593-3703 URL: www.ajinextek.com E-mail: marketing@ajinextek.com

Analog Output Function Module RTEX-A04H

Features

Slave Analog output function extension module for RTEX

- Used by connecting to PCI-R1604 RTEX communication master board
- Max 32 slave modules can be connected (node ID setting is required)
- 4 channels analog output control



Specification

Item	Description				
RTEX-AO4H					
Module function	RTEX based slave 4ch analog output function module				
NODE ID setting	Decimal number rotary switch × 2 (0 to 31)				
Mounting Method	Standard 35 mm DIN rail mounting				
Power supply / current consumption	24 VDC / Max. 500 mA (TB1 Connection to utside Module)				
LED display	Power (ellow), Live (reen), Error (Red), Com (ellow)				
Number of output channels	s 4 channels				
Resolution	16 bit				
Analog output	utput 4 channel Voltage mode : -10V to +10V Resolution : 16 Bit Sampling speed :100KHz Connector : Phoenix 10 X 1 (MCD 1,5/10-G1F-3,81)				
Software					
User Agent Software	EzSoftware RM				
Operating System	Windows XP (32bit, 64bit), Windows 2000				
General specification					
Dimension H D W	100 × 90 × 40 mm				
Weight	246 g				
Operation temperature 0°C to 60°C					

Contact to: AJINEXTEK CO., LTD.

9-3, Horim-dong, Dalseo-gu, Daegu-city, Korea TEL: +82-593-3700 FAX: +82-593-3703 URL: www.ajinextek.com E-mail: marketing@ajinextek.com



Anywire Anywire Corporation



RTEX/AnyWire Gateway AG42-R1

Features

Connect AnyWire Reduced Wiring I/O System to RTEX

- AnyWire reduced wiring system has Dual-Bus function which transfers DI/ and AI/ on the same transfer line but independent of each other.
- AnyWire reduced wiring system is cable free specification and uses general purpose wires
- Layout free, e.g. T branch, multi drop and tree wiring
- Simple one-touch connection, branch and extension by using insulation displacement connector
- Max. No. of I/ points is 2560 and max. No. of units connected to I/O terminal is 128
- Max. connecting route length 1000 m

Specification

Item			Description				
RTEX	No. of exclu	sive blocks	3 to 11 (depending on No. of points used)				
	Effective dat transmission	ta n rate	183 kbps/256 points (@ transfer clock: 62.5 kHz)				
	Transmissio	n scheme	Full quadruplex total frame cyclic system				
	Synchroni a system	ition	Frame/bit synchronization system				
	Data length/	frame	1-bit to 1024-bit				
	Connection	topology	Bus (multi drop, T branch, tree)				
	Transmissio	n protocol	Dedicated protocol (AnyWireBus)				
	Error contro	I	Double check				
	Max. No. of	Bit-Bus	512 points (IN 256 points + OUT 256 points)				
Anyv	connecting I/O points ¹	Word-Bus	2048 points (IN 1024 points + OUT 1024 points) or 128 words (IN 64 words + OUT 64 words)				
Vire	Max. No. of ounits	connected	128 (Total of Bit-Bus terminals and Word-Bus terminals)				
	Max. cycle ti	ime ²	[0.85 ms/128 points], [1.4 ms/256 points], [2.4 ms/512 points], [4.4 ms/1024 points] (transfer clock @62.5 kHz)				
	RAS functio	n	Transmission line breakage position detection and transmission line short-circuit detection				
	Transmission cable		Cable free • General purpose (VCTF) 2-core /0.75 to 1.25 mm ² : transmission only (D,) • General purpose (VCTF) 4-core /0.75 to 1.25 mm ² : including power supply (D, , 24 V, 0 V) • Other general purpose cables /0.9 to 1.25 mm ² : e.g. parallel • Special flat cable /0.75 to 1.25 mm ² : including power supply (D, , 24 V, 0 V)				
	Max. transm distance 4	ission	[1 km/7.8 kHz] [500 m/15.6 kHz] [200 m/31.3 kHz] [100 m/62.5 kHz]				

1: The number depends on the master. 2: Typical values at the top speed. 3: Diameter varies with transmission distance. 4: Distance is the cable total length.

Contact to: Anywire corporation Headquarters

8-1 Shimoinden, Inouchi, Nagaokakyo-city, Kyoto 617-0813, Japan URL: http://www.anywire.jp/ TEL: +81-75-956-1611(Japanese only) FAX: +81-75-356-1613 E-mail: info e@anywire.jp nly Japanese is used for inquiry over the phone. When making an inquiry in English, send it to: info e@anywire.jp.





Asahi Engineering Co., Ltd.

2-phase Microstep Drive D4610

Features

Leading Edge High Speed Motion Network RTEX At Low Cost

High performance CPU enhances drive capability

- Step-out detection
- Triangle drive prevention
- · Motor over current protection
- Vibration suppression
- Brake control
- · Closed loop control by encoder signal
- RTEX in motion network
- Network can connect up to 2 axes depending on master specification)
- Simultaneous multiaxial control within 1 ms communication period



Specification

	Item	Description				
Pow	er supply	Main power supply: 24 VDC 10 (4.0 A max.) Sensor power supply: 24 VDC 10 (0.1 A)				
Appl	icable motor	2.55 A/phase or less 2-phase HB type stepping motor				
Drivi	ng capacity	2.55 A/phase				
Micr	o step resolution	Basic step divided by 200 (for 40,000 p/r basic step 1.8 deg motor)				
Com	munication specification	Realtime Express (RTEX)				
Inpu	t signal	Sensor input 4 (H ME, EX, CWLS, CCWLS), encoder input and stop input				
Outp	ut signal	Brake output and alarm output				
Protective function		ver current, power supply voltage monitoring and step-out detection				
	Ambient temperature	0 to 50°C (no freezing), Storage: 20 to 60°C (no freezing)				
En	Ambient humidity	90 RH max. (no dewing). Storage: 90 RH max. (no dewing)				
/iro	Atmosphere	Indoor (no direct sunshine). No corrosive gas, flammable gas, oil mist, dust, etc.				
nme	Altitude	Max. 1,000 m above sea level				
nt	Operating vibration shock environment	Max. 2 (10 to 250 Hz, in X, , direction 1 hour), max. 10 (1)				
Outli	ne dimensions mm	160 × 92 × 29				
Mass		Approx. 300 g				

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Contact to: Asahi Engineering Co., Ltd. Kodaira Works

3-3-22, Gakuen-Higashicho, Kodaira-shi, Tokyo 187-0043, Japan TEL: +81-42-342-4422 FAX: +81-42-342-4423

RTEX <Slave>

RTEX <Slave>

URL: http://www.asahi-engineering.co.jp/ E-mail: ae-sales@asahi-engineering.co.jp

RTEX <Slave>



Slave Family

Features



Specification

MCRTEX2sd



2-axis pulse output board

- ne board can control 2-axis motor (occupies 2 blocks)
- 1 pulse/2 pulse/2-phase pulse output is possible. Pulse train input type drive can be connected, regardless of stepping or servo. (Differential output)
- Up to 8 Mpps pulse can be output, enabling high speed, high resolution control
- · Feedback pulse counting is possible. UP/D WN, A/B phase (multiplied by 1/2/4) signals can be used for counting.



INRTEX16sd/OTRTEX16sd

DI board and DO board

INRTEX16sd Input configuration : Photocoupler isolated • No. of inputs : 16

Rated voltage: +24 VDC OTRTEX16sd Output configuration

: Photocoupler isolated open collector (sink) No. of outputs: 16 Output rated voltage : +24 VDC utput rated current : 100 mA Max.

Contact to: HI-P Tech Corporation Sales Dept.

1-27-23, Higashitokorozawa, Tokorozawa-shi, Saitama 359-0021, Japan TEL:+81-4-2951-5381 FAX:+81-4-2951-5383 URL: http://www.hptec.co.jp/



2-ch analog input board

ADRTEX2sd

No. of input channels: 2 Input configuration

: Differential/single end • Input range : 10 V, 5 V, 0-0 V Resolution : 12 bits Conversion mode : Free run/external trigger Manufacturer/ Prime Motion Prime Motion Inc.

General Purpose 2/ 2 Input/Output Board InterMotion Series JOY-RIO 2 2

Features

- Single board with 32 IN points and 32 UT points
- 10 PIN connector for 8-point IN and 8-point OUT. Can be directly connected to terminal block PRS-DG10-O8 (TOYOGIKEN Co., Ltd).
- 24 V DC supply





Specification

Item Description					
Input	32 points (8 points × 4 ports), 24 VDC, 4.7 k Ω				
Output	32 points (8 points × 4 ports), 24 VDC, 100 mA				
Max. No. of connectable boards	6 (IN 192 points, UT 192 points)				

Contact to: Prime Motion Inc. (InterMotion - Special site: http://www.intermotion.jp) 1134-12, Akaho, Komagane-shi, Nagano, 399-4117, Japan TEL:+81-265-82-2990 FAX:+81-265-82-2292 URL: http://www.primemotion.com/



RS4 Communication MINAS A A

AE-LINK

RS485 open network

- PTP control by servo built-in positioning function
 - Positioning unit is not required
 - Universal RS485 communication without using specific IC
 - Low cost with Ethernet cable



[Typical system configuration]



•Application specific IC is not required.



c IC •Cable cost 1/10



conventional AE-LIN product

Network specification

Item	Description
Communication rate	38.4/307.2 kbps
Physical layer	RS485 half duplex
Cable	Shielded twisted pair cable
Communication period	Approx. 1 ms/axis (@307.2 kbps)
Topology	Bus (terminating resistor is required)
Operating command	Target position

Features of drive

Simple setup

Thanks to the proprietary real time auto tuning, gain can be set easily by simple operation.

Quick response

High rigid mechanics can be driven at higher rate, i.e. speed response frequency of 1000 Hz, increasing production efficiency.

Low vibration

Vibration suppression control enables a low rigidity mechanics driven at low vibration.

Compact

Industry's lowest level compact size (1/2 of Panasonic precedent product), contributing space saving of the site.

High precision

The standard model can response to full closed control, achieving high precision positioning.

Expandable

For feedback scale, common A/B/Z phase pulse signal type can be used.

[External view] Dimensions (mm): W40 × H150 × D132 (A frame)





Drive list

		Motor rated output											
		50 W	100 W	200 W	400 W	750 W	1 kW	1.5 kW	2 kW	3 kW	4 kW	5 kW	7.5 kW
	Single phase	A	Α	В	С								
	100 to 115 VAC	MADD T1105A	MADD T1107A	MBDD T2110A	MCDD T3120A								
riv	Single phone	l I	Ą	А	В								
e pov	200 to 240 VAC	MA T12	DD 05A	MADD T1207A	MBDD T2210A								
ler	Single/2 phase					С	[)					
ddns	200 to 240 VAC					MCDD T3520A	MD T55	DD 40A					
2	2 shaaa								E	F	F	-	G
	200 to 230 VAC								MEDD T7364A	MFDD TA390A	MF TB3	DD A2A	MGDD TC3B4A

Upper line: Frame size symbol Lower line: Typical drive part number

Note: Some motors do not match part numbers in the table.

Applicable standards







PLC Direct Access AE-LINK Motion Controller

PI-1200 (RS-232C) / PI-1300 (Ethernet)

Features

Building a motion network at low cost under PLC

PLC direct access

The controller runs the motion program installed in PI while accessing PLC data register.

- Preparation of ladder program for communication is not required on PLC.
- No CPU burden on PLC.
- Simple motion control through data register
- Motors can be controlled by operating PLC data register.
- Multiaxial motors can be controlled/monitored by simply operating numeric values on the data register.
- PLC operator having no knowledge on communication of motion (AE-LINK) can control the motor.

Stepping motor can be mixed

The motion network can contain servo motor and stepping motor.



Specification

Item	Description
Power supply	24 VDC 10 300 mA MAX
Operating temperature and humidity	0 to 50 C, 90 RH max. (no dewing)
Outline dimensions (mm)	W24 × D110 × H150 (PI-1200), W25 × D109 × H184 (PI-1300)
	PI-1200: RS-232C 115.2 kbps/38.4 kbps Conforms to various corporate protocols.
Communication with PEC	PI-1300: Ethernet 10/100 BASE-T Conforms to various corporate protocols.
Program loader	RS-232C 38.4 kbps
Control signal I/O	Initialization input, system alarm output and node alarm output
Motion network	AE-LINK 307.2 kbps/38.4 kbps (Selection on DIP switch)
No. of connection nodes	Max. 16
Motion control	PTP (Point to Point)

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Contact to Asahi Engineering Co. Ltd. Kodaira Works

3-3-22, Gakuen-Higashicho, Kodaira-shi, Tokyo 187-0043, Japan TEL: +81-42-342-4422 FAX: +81-42-342-4423 URL: http://www.asahi-engineering.co. p/ E-mail: ae-sales@asahi-engineering.co. p

AE-LINK Compatible Stepping Motor Drive Series

Features

Building servo and step mixed motion network at a low cost

- Drive has built-in software NC, requiring no host NC controller
- High performance CPU enhances drive functionalities
 - · Built-in origin return function
- Triangle driving prevention function
- Step-out detection function
- Motor over current protection function
- Vibration suppression function
- Up to 31 axes can be connected to the same network (Depending on the master specification)









Specification

Part No.	Input power supply	Applicable motor	Driving capacity	Step-out detection	Drive outline
D3910S	24 VDC	2-phase	1.5 A/phase		Board type micro step drive
D3080S1	24 to 48 VDC	2-phase	2.55 A/phase	0	High precision micro step drive
D3080S2	24 to 48 VDC	2-phase	5.1 A/phase	0	High precision high power micro step drive
D4390S	100 VAC	2-phase	2.55 A/phase	0	AC supply input high precision micro step drive
D4370S	24 VDC	5-phase	1.5 A/phase		Board type half step drive
D4130S	24 VDC	5-phase	1.5 A/phase		High precision micro step drive

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AE-LINK Master

PI-1300

PI-1200

Linear motor control

RTEX Compatible AE-LINK Compatible

High precision and high speed advancement of A5 series linear control drive

Motor

 Compatible with various motors such as 3-phase cored/coreless, shaft motor and DD motor

Scale

Compatible with serial communication incremental/absolute and A/B/Z phase scale

Magnetic pole detection

Compatible with both with and without CS signal (automatic detection)

Setup

Automatic setup of magnetic pole, scale direction, gain, etc.



[Lineup] Products of the following two specifications are available with the distinguishable symbol, L01 or LA1 placed at the end of the part number.

detected

cot



RTEX Compatible Linear Control Drive





AE-LINK Compatible Linear Control Drive

[Typical system configuration]



[Typical system configuration]



Drive List (Common to A5L and A5NL)

Power supply	Drive Part No. (Note)	Motor rated current [Arms]	Motor max. current [Arms]	
	MADHT1105***	1.2	3.6	ĺ
Single	MADHT1107***	1.7	5.1	
phase 100 V	MBDHT2110***	2.5	7.5	
100 V	MCDHT3120***	4.6	13.8	
	MADHT1505***	1.2	3.6	
0	MADHT1507***	1.6	4.8	ĺ
Single/	MBDHT2510***	2.6	7.8	
3-priase	MCDHT3520***	4.1	12.3	
200 V	MDDHT3530***	5.9	16.9	
	MDDHT5540***	9.4	28.2	

Power supply	Drive Part No. (Note)	Motor rated current [Arms]	Motor max. current [Arms]	
	MEDHT7364***	13.4	40.2	
3-phase 200 V	MFDHTA390***	18.7	56.1	
	MFDHTB3A2***	33.0	84.8	
	MGDHTC3B4***	44.0	116.6	
	MHDHTC3B4***	66.1	167.2	
	MDDHT2407***	1.5	4.5	
	MDDHT2412***	2.9	8.7	
	MDDHT3420***	4.7	14.1	
3-phase	MEDHT4430***	6.7	19.7	
400 V	MFDHT5440***	9.4	28.2	
	MFDHTA464***	16.5	42.4	
	MGDHTB4A2***	22.0	58.7	
	MHDHTB4A2***	33.1	83.7	

Note: Trailing *** in the part number is replaced with the following symbol: A5L: for L01 or LA1, A5NL: for NL1 (standard) or N91 (with safety I/F option).

For A4AL, consult us.

Manufacturer/ NPM Nippon Pulse Motor Co. Ltd.



High Performance Linear Stage SLP Series

Features

- Varied selection to meet diverse needs (SLP15/SLP25/ SLP35)
- High thrust, high speed, quick response, high precision, long stroke
- Coreless design for cogging free (constant velocity)
- Contactless power driving design for low noise, long life and maintenance free
- Double slider design helps a great deal in performing complicated operation and saving space



Specification

	Item	Unit		Description		
Part No.			SLP15	SLP25	SLP35	
Resolution		mm	0.001 (HEIDENHAIN GmbH LIDA279)	0.001 (HEIDENHAIN GmbH LIDA279)	0.001 (HEIDENHAIN GmbH LIDA279)	
Rated thrus	st	N	17	80	185	
Acceleratio	n thrust	Ν	90	340	970	
Rated curre	ent	А	0.51	1.2	2.7	
Acceleratin	g current	А	2.7	5.1	14.4	
Thrust con	stant	N/A	33	66	68	
Back electro	motive force constant	V/m/s	11	22	22	
Resistance		Ω	56	22	7.2	
Inductance		mН	24	31	12	
Magnetic p	itch (N-N)	mm	60	90	120	
Max. accele	eration	G	3.5	3.5	3.5	
Max. veloci	ty	m/s	3.0 3.0		3.0	
Bi-Direction	nal repeatability	mm	0.0005	0.0005	0.0005	
Max. load	Hori ontal placement	kg	5	30	60	
capacity	Wall mounted	kg	3	15	30	
Stroke	Single slider	mm	100 to 1300 (In 100 step)	200 to 1200 (In 100 step)	300 to 1200 (In 100 step)	
SHOKE	Double slider	mm	100 to 1200 (In 100 step)	200 to 1000 (In 100 step)	300 to 900 (In 100 step)	
Operating a	ambient temperature	°C	0 to +40	0 to +40	0 to +40	
Operating a	ambient humidity		20~80 (No dewing)	20~80 (No dewing)	20~80 (No dewing)	
Storage ten	nperature	°C	-20 to +60	-20 to +60	-20 to +60	
		200 V	MADHT1505L * *	MADHT1507L * *	MCDHT3520L * *	
WINAS ASL		100 V	MADHT1105L * *	MADHT1107L * *	MCDHT3120L * *	

Contact to Nippon Pulse Motor Co. Ltd.

16-13, 2-chome, Hongo, Bunkyo-ku, Tokyo 113-0033, Japan TEL: +81-3-3813-8841 FAX: +81-3-3813-8550 URL: http://www.pulsemotor.com/

Manufacturer/ NPM Nippon Pulse Motor Co. Ltd.

for A5L, A5NL, A4AL

Linear Shaft Motor

S series/L series

Features

- High thrust (3100N)
- High-speed driving (6.3 m/s) Low-speed driving (8 µm/s)
- Noncontact power drive for low noise, long life and maintenance free (Mechanical contact is only on linear guide: use of air slider eliminates all contacts.)
- Coreless design for cogging free (constant velocity)
- Simple structure for easy mounting and unitizing
- Highly resistant to environment (operative in water and vacuum)
- Easily replaces ball screw system
- More compact and lightweight than other competitive linear motors

Specification

		SO	180 seri	es	S1	20 seri	es	S1	60 serie	es	S20	IO seri	ies		\$25	0 series	5		S	320 se	ries		
Item	Unit	S080D	S080T	S080Q	S120D	S120T	S120Q	S160D	S160T	S160Q	S200D	S200T	S200Q	S250D	S250T	S250Q	\$250X	S320	D \$320	T S320		320X	
Rated thrust	N	1.8	2.7	3.5	4.5	6.6	8.9	10	15	20	18	28	38	40	60	75	140	56	85	113	3 2	226	
Rated current	A	0.8	0.8	0.8	0.4	0.4	0.4	0.6	0.6	0.6	0.6	0.6	0.6	1.3	1.3	1.3	2.4	1.2	1.2	1.2	2 3	2.5	
Acceleration thrust	N	7.2	10.7	14	18	27	36	40	60	81	72	112	152	160	240	300	560	226	338	3 45 ⁻	1 9	902	
Accelerating current	A	3.4	3.4	3.4	1.6	1.6	1.6	2.5	2.5	2.5	2.4	2.4	2.4	5.1	5.1	5.1	9.6	5.0	5.0	5.0) 9	9.96	
Thrust constant Kf	N/A	2.1	3.2	4.2	11	17	22	16	24	33	31	47	64	31	47	59	58	45	68	91		91	
Back electromotive force constant	V/m/s	0.7	1.1	1.4	3.7	5.5	7.4	5.4	8.1	11	10	16	21	10.4	16	20	19	15	23	30		30	
Electric resistance (line)	Ω	4.7	6.8	9.0	37.0	54.0	73.0	21.0	33.0	43.0	28.7	43.0	56.0	7.8	12.0	15.0	7.5	11.0	0 17.	23.	0 1	1.5	
Inductance (line)	mH	0.7	1.0	1.3	12.0	18.0	24.0	8.2	12.0	16.0	19.3	29.0	39.0	9.8	15.0	19.0	9.5	17.0	0 26.	34.	0 1	7.0	
Thermal resistance Kq	°C/W	33.2	22.9	17.3	18.6	12.7	9.4	13.6	8.7	6.7	11.0	7.3	5.6	8.6	5.6	4.5	2.5	6.7	4.7	3.6	; .	1.5	
Forcer Length	mm	40	55	70	64	88	112	80	110	140	94	130	166	120	165	210	390	160) 220	280) 5	520	
Forcer Width	mm	20	20	20	25	25	25	30	30	30	40	40	40	50	50	50	50	60	60	60		60	
Forcer Weight	kg/f	0.05	0.06	0.08	0.09	0.12	0.16	0.15	0.20	0.30	0.30	0.50	0.70	0.80	1.1	1.5	2.9	1.2	1.7	2.2	2 4	1.20	
ар	mm	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.50	0.75	0.75	0.75	0.75	0.75	0.75	0.75	1.0	0 1.0	0 1.0	0 1	.00	
Pipe outside diameter	mm	8	8	8	12	12	12	16	16	16	20	20	20	25	25	25	25	32	32	32		32	
Magnetic pitch (N-N)	mm	30	30	30	48	48	48	60	60	60	72	72	72	90	90	90	90	120) 120	120) 1	120	
Max. manufacturable stroke	mm	230	215	200	1541	1517	1493	1755	1745	1715	2471	2435	2399	2615	2570	2525	1710	231	0 225	0 219	0 1	950	
	200 V					м	ADHT1	505L*	*					MAD	HT1507	1**	MBDH [*] 2510L*	г * ма	DHT15	i07L**	ME 251	3DHT 0L**	
Applicable drive	100 V					MADHT1105L** MAI				MAD	HT1107	L**	MBDH [*] 2110L*	г * ма	DHT11	07L**	ME 211	3DHT 0L**					
		S350 series																					
		5	6350 se	ries		S427 s	series		S435 s	eries		S500	0 serie	s	S600	series	Ľ	250 ser	ies	L3	20 ser	ies	
Item	Unit	5 S350D	6350 se S350T	ries S3500	Q S42	S427 s 27D S42	series !7T S42	7Q S43	S435 s 5D S435	eries iT S435	Q S500	S500 DD S	0 serie 6500T	s S500Q	S600 S605T	series S6050	L: 2 L250D	250 ser L250T	ies L250Q	L3 L320D	20 ser L320T	ies L320Q	
Item Rated thrust	Unit N	5 S350D 104	S350 se S350T 148	ries \$3500 190	Q S42	S427 s 27D S42 00 15	series 27T S42 i0 20	7Q S43 10 11	S435 s 5D S435 6 175	eries iT S435 5 233	Q S500	S500 DD S 9 .	0 serie 5500T 440	s \$500Q 585	S600 S605T 610	S6050 780	L: 2 L2500 34	250 ser L250T 52	ies L250Q 69	L3 L320D 55	20 ser L320T 82	ies L320Q 109	
Item Rated thrust Rated current	Unit N A	5350D 104 1.5	S350 se S350T 148 1.5	eries \$3500 190 2.7	Q S42 10 3.	S427 s 27D S42 00 15 .0 3.	series 27T S42 60 20 0 3.	7Q S43 10 11 0 3.0	S435 s 5D S435 6 175 0 3.0	eries 57 S435 5 233 9 3.0	Q S500 281 3.8	S500 DD S 9 -	0 serie 5500T 440 5.8	s \$500Q 585 7.7	S600 S605T 610 8.6	series \$6050 780 8.4	L: 2 L2500 34 1.3	250 ser L250T 52 1.3	ies L250Q 69 1.3	L3 L320D 55 1.3	20 ser L320T 82 1.3	ies L320Q 109 1.3	
Item Rated thrust Rated current Acceleration thrust	Unit N A N	\$ \$350D 104 1.5 416	S350 se S350T 148 1.5 592	eries \$3500 190 2.7 760	2 S42 10 3. 40	S427 s 27D S42 00 15 .0 3. 00 60	series 27T S42 10 20 0 3. 10 80	70 S43 10 11 0 3.1 10 46	S435 si 5D S435 6 175 0 3.0 4 700	eries 51 \$435 5 233 0 3.0 0 932	Q S500 289 3.8 1115	S500 DD S 9 - 3 - 6 1	0 serie 5500T 440 5.8 1760	s \$500Q 585 7.7 2340	S600 S605T 610 8.6 2400	series \$6050 780 8.4 3100	2 L2500 34 1.3 0 138	250 ser L250T 52 1.3 207	ies L250Q 69 1.3 276	L3 L320D 55 1.3 218	20 ser L320T 82 1.3 327	ies L320Q 109 1.3 436	
Item Rated thrust Rated current Acceleration thrust Accelerating current	Unit N A N A	\$3500 104 1.5 416 6.0	S350 se S350T 148 1.5 592 6.0	eries \$3500 190 2.7 760 10.8	2 S42 10 3. 40 3 12	S427 s 27D S42 00 15 .00 3. .00 60 2.00 12	series 27T S42 i0 20 i0 3. i0 80 .0 12	7Q S43 0 11 0 3.0 0 46 .0 12	S435 sec 5D S435 6 175 0 3.0 4 700 .0 12.0	eries 57 \$435 5 233 0 3.0 0 932 0 12.0	Q S500 289 3.8 115 0 15.	S500 DD S 9 - 3 - 6 11 2 2	0 serie 500T 440 5.8 1760 23.2	s \$500Q 585 7.7 2340 30.8	S600 S605T 610 8.6 2400 34.0	Series \$6050 780 8.4 3100 34.0	 L2500 34 1.3 138 5.2 	250 ser L250T 52 1.3 207 5.2	ies L250Q 69 1.3 276 5.2	L3 L320D 55 1.3 218 5.0	20 ser L320T 82 1.3 327 5.0	ies L320Q 109 1.3 436 5.0	
Item Rated thrust Rated current Acceleration thrust Accelerating current Thrust constant Kf	Unit N A N A N/A	\$350D 104 1.5 416 6.0 69	S350 se S350T 148 1.5 592 6.0 99	eries \$3500 190 2.7 760 10.8 70	Q S42 10 3. 40 3 3	S427 s 27D S42 00 15 .0 3. .00 60 2.00 12 3 5	series 27T \$42 i0 20 0 3. 10 80 .0 12 0 6'	70 S43 10 11 0 3.1 10 46 .0 12 7 39	S435 sec 5D S435 6 175 0 3.0 4 700 .0 12.0 9 58	eries 6T \$435 5 233 0 3.0 0 932 0 12.0 78	Q S500 288 3.8 1115 0 115. 76	S500 DD S 9 4 3 4 66 1 2 2 3	0 serie 5500T 440 5.8 1760 23.2 76	s \$500Q 585 7.7 2340 30.8 76	S600 S605T 610 8.6 2400 34.0 71	series \$6050 780 8.4 3100 34.0 93	L2500 34 1.3 138 5.2 27	250 ser L250T 52 1.3 207 5.2 40	ies L250Q 69 1.3 276 5.2 53	L3 L320D 55 1.3 218 5.0 44	20 ser L320T 82 1.3 327 5.0 65	ies L320Q 109 1.3 436 5.0 87	
Item Rated thrust Rated current Accelerating current Thrust constant Kf Back electromotive force constant	Unit N A N A N/A V/m/s	\$3500 104 1.5 416 6.0 69 23	S350 se S350T 148 1.5 592 6.0 99 33	eries \$3500 190 2.7 760 10.8 70 23	Q S42 10 3. 40 8 12 3 12	S427 s 27D S42 00 15 00 3. 00 60 2.0 12 3 50 1 1	series 277 \$42 20 20 00 3. 10 80 .00 12 00 6 77 24	7Q \$43 10 11 0 3.1 10 46 .0 12 7 39 2 13	S435 state 5D S435 6 175 0 3.0 4 700 .0 12.0 9 58 3 19	eries T \$435 5 233 0 3.0 0 932 0 12.0 78 26	Q \$500 289 3.8 115 0 15. 76 25	S500 DD S 9 - 3 - 66 1 2 2 5 -	0 serie 500T 440 5.8 1760 23.2 76 25	s \$500Q 585 7.7 2340 30.8 76 25	\$600 \$605T 610 8.6 2400 34.0 71 24	series \$6050 780 8.4 3100 34.0 93 31	 L2500 34 1.3 138 5.2 27 8.8 	250 ser L250T 52 1.3 207 5.2 40 13	ies L250Q 69 1.3 276 5.2 53 18	L3 L320D 55 1.3 218 5.0 44 15	20 ser L320T 82 1.3 327 5.0 65 22	ies L320Q 109 1.3 436 5.0 87 29	
Rated thrust Rated current Acceleration thrust Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line)	Unit N A N A N/A V/m/s Ω	\$ \$350D 104 1.5 416 6.0 69 23 13.8	S350 se S350T 148 1.5 592 6.0 99 33 20.2	ries \$3500 190 2.7 760 10.8 70 23 6.9	2 S42 10 3. 40 3 12 3 11 2.	S427 S42 27D S42 00 15 00 3. 00 60 2.0 12 3 5 11 1 .7 3.	Series 277 \$42 60 20 00 3. 00 80 .00 12 00 6 77 21 99 5.	70 \$43 10 11 00 3.0 100 46 .00 12 7 39 2 13 2 2.1	S435 si 5D S435 6 175 0 3.0 4 700 .0 12.0 9 58 3 19 7 3.9	State State <th< th=""><th>Q \$500 285 3.8 115 15. 76 25 4.4</th><th>S500 DD S 9 - 3 66 1 2 2 5 5 6 1 4</th><th>0 serie 500T 440 5.8 1760 23.2 76 25 3.3</th><th>s \$500Q 585 7.7 2340 30.8 76 25 2.2</th><th>\$600 \$605T 610 8.6 2400 34.0 71 24 1.7</th><th>series \$6050 780 8.4 3100 34.0 93 31 2.2</th><th>L 2 L250D 34 1.3 138 5.2 27 8.8 8.8 8.4</th><th>250 ser 52 1.3 207 5.2 40 13 13</th><th>ies L250Q 69 1.3 276 5.2 53 18 17</th><th>L3 L320D 55 1.3 218 5.0 44 15 12</th><th>20 ser L320T 82 1.3 327 5.0 65 22 17</th><th>L320Q 109 1.3 436 5.0 87 29 23</th></th<>	Q \$500 285 3.8 115 15. 76 25 4.4	S500 DD S 9 - 3 66 1 2 2 5 5 6 1 4	0 serie 500T 440 5.8 1760 23.2 76 25 3.3	s \$500Q 585 7.7 2340 30.8 76 25 2.2	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7	series \$6050 780 8.4 3100 34.0 93 31 2.2	L 2 L250D 34 1.3 138 5.2 27 8.8 8.8 8.4	250 ser 52 1.3 207 5.2 40 13 13	ies L250Q 69 1.3 276 5.2 53 18 17	L3 L320D 55 1.3 218 5.0 44 15 12	20 ser L320T 82 1.3 327 5.0 65 22 17	L320Q 109 1.3 436 5.0 87 29 23	
Item Rated thrust Rated current Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line)	Unit N A N/A V/m/s Ω mH	5350D 104 1.5 416 6.0 69 23 13.8 21.8	S350 se S350T 148 1.5 592 6.0 99 33 20.2 33.0	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9	2 S42 10 3. 40 8 12 3 12 3 1 2.	S427 s 27D S42 00 15 00 3. 00 60 1.0 12 3 51 1 11 7 3. 7 1	series 277 \$42 60 20 00 3. 10 80 .0 12 00 6 77 22 99 5. 11 11	7Q S43 00 11 00 3.9 100 466 .00 122 77 39 22 133 22 22.7 55 7	S435 si 5D S435 6 175 0 3.0 4 700 0 12.0 9 58 3 19 7 3.9 11	eries T \$435 5 233 0 3.0 0 932 0 12.0 78 26 1 5.2 15	Q \$500 289 3.8 115 0 15. 76 25 4.4 27	S500 D S 9 - 3 - 66 1 2 2 3 - 5	0 serie 5001 440 5.8 1760 23.2 76 25 3.3 20	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7 10	series \$6050 780 8.4 3100 34.0 93 31 2.2 13	L L250D 34 1.3 1.3 5.2 27 8.8 8.4 9.2	250 ser L250T 52 1.3 207 5.2 40 13 13 13 14	ies L250Q 69 1.3 276 5.2 53 18 17 18	L3 L320D 55 1.3 218 5.0 44 15 12 14	20 ser L320T 82 1.3 327 5.0 65 22 17 21	ies 1320Q 109 1.3 436 5.0 87 29 23 28	
Item Rated thrust Rated current Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq	Unit N A N/A V/m/s Ω mH °C/W	\$ \$350D 104 1.5 416 6.0 69 23 13.8 21.8 3.5	S350 se S350T 148 1.5 592 6.0 99 33 20.2 33.0 2.4	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2	Q \$42 10 3. 40 12 3 12 3 1 2 7 4 4	S427 s 27D S42 00 15 00 3. 00 600 2.0 12 3. 50 1 11 .7 3. 7 11 .6 3.	series 77 \$42 60 20 0 3. 10 80 .0 12 0 6 7 21 9 5. 1 11 2 2.	7Q S43 10 11 0 3 10 46 .0 12 7 39 2 13 2 2 5 7 4 4.4	S435 si 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 6	eries T \$435 5 233 0 3.0 0 932 0 12.0 78 26 0 5.2 15 2.4	Q \$500 288 3.8 115 0 15. 76 25 4.4 27 1.5	S500 DD S 9 - 3 - 66 11 22 2 3 - 5 - 5 - 7 -	0 serie 5001 440 5.8 1760 23.2 76 25 3.3 20 1.0	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7 10 0.90	series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.700	L: 2 L2500 34 1.3 1.3 5.2 27 8.8 8.4 9.2 7.8	250 ser 250 ser 52 1.3 207 5.2 40 13 13 14 5.2	ies L250Q 69 1.3 276 5.2 53 18 17 18 3.9	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1	20 ser L320T 82 1.3 327 5.0 65 22 17 21 4.1	ies 13200 109 1.3 436 5.0 87 29 23 28 3.1	
tem Rated thrust Rated current Accelerating current Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Length	Unit N A N/A V/m/s Ω mH °C/W mm	53500 104 1.5 416 6.0 69 23 13.8 21.8 3.5 160	S350 se S350T 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2 280	2 542 10 3. 40 8 12 3 12 3 12 3 12 3 40 8 12 3 7 40 7 4. 22	S427 s 27D S42 00 15 00 3. 00 60 2.0 12 3 50 1 1' .7 3. .7 1' .6 3. 20 31	series 27T \$42 i0 20 i0 3. i0 80 .0 12 0 6 7 2: 9 5. 1 1! 2 2. 0 40	70 S43 10 11 0 3.0 10 46 .0 12 7 39 2 13 2 2.2 5 7 4 4.0 00 22	S435 sec 5D S435 6 175 0 3.0 4 700 .0 12.0 9 58 83 19 7 3.9 6 3.2 0 310	eries T \$435 5 233 0 3.0 0 932 0 12.1 78 26 0 5.2 15 2 2.4 0 400	Q \$500 3.8 3.8 115 0 15. 76 25 4.4 27 1.7 0 24	S500 D S 9 - 3 66 1 2 2 5 6 7 7 7 0	0 serie 500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420	S600 S605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430	series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.70 550	L: 2 L2500 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120	250 ser 250 ser 52 1.3 207 5.2 40 13 13 14 5.2 165	ies L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160	20 ser L320T 82 1.3 327 5.0 65 22 17 21 4.1 220	ies L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280	
Item Rated thrust Rated current Acceleration thrust Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Length Forcer Width	Unit N A N/A V/m/s Ω mH °C/W mm mm	\$ \$350D 104 1.5 416 6.0 69 23 13.8 21.8 3.5 160 60	S350 se S350T 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220 60	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2 280 60	Q \$42 10 3. 40 12 3 1 2 3 1 2. 3 1 2 3 4 4 4 4 3 3 3 1 4 2 8 3 3 3 4 4 4 4 4 4 8 3	S427 s 27D S42 00 15 00 3. 00 60 1.0 12 3 51 1 1 .7 3. .7 1 .6 3. 20 31 00 8	Series 277 \$42 60 20 60 3. 100 80 .00 12 00 6 77 24 99 5. 11 11 22 2. 00 40 00 8	70 \$43 10 11 0 3.1 10 46 .0 12 7 38 2 13 2 2.2 5 7 4 4.1 10 22 00 80	S435 sc 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 6 6 3.10 0 310 0 800	eries T \$435 5 233 0 3.0 0 932 0 12.1 78 26 1 5.2 15 2 2.4 0 400 80	Q \$500 289 3.8 1115 0 15. 76 25 4.4 27 1.7 0 244 105×	S500 DD S 9 - 3 - 66 1 2 2 2 5 - 5 - 7 - 7 - 7 - 0 - 3 100 10	0 serie 500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 5×100	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 125/12	series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.700 5500 125/12	L: 2 L2500 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120 20 50	250 ser 250 ser 52 1.3 207 5.2 40 13 13 13 14 5.2 165 50	ies L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60	20 ser L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60	ies L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280 60	
Item Rated thrust Rated current Accelerating current Thrust constant K1 Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Length Forcer Width Forcer Weight	Unit N A N/A V/m/s Ω mH °C/W mm mm kg/f	\$ \$350D 104 1.5 416 6.0 69 23 13.8 21.8 3.5 160 60 1.3	350 se \$350T 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220 60 1.9	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2 280 60 2.4	Q \$42 10 3. 40 12 3 1 2 3 1 2. 4 22 8 3. 3 3	S427 s 27D S42 00 15 00 3. 00 60 1.0 12 3 56 1 1' .7 3. .7 1 .6 3. .20 31 0 8 .0 4.	Series 277 \$42 60 20 60 20 60 3. 60 80 70 82 77 24 99 5. 11 11 22 2. 0 40 0 88 2 5. 30 82	70 \$43 70 11 0 3.1 10 3.1 10 46 .0 12 7 39 2 13 2 2.5 75 7 4 4.4 10 22 00 80 4 3.1	S435 ss 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 3.2 0 310 0 800 0 4.2	eries T \$435 5 233 1 3.0 0 932 0 12.1 78 26 1 5.2 15 2 2.4 0 400 80 2 5.4	Q \$500 289 3.8 115 0 15. 76 25 4.4 27 1.7 1.7 1.7 105× 105× 105×	S500 DD S 9 - 3 - 66 1 2 2 3 - 66 1 2 2 3 - 6 1 2 2 3 - 6 1 2 2 3 - 6 1 7 - 1 0 - 1 1 2 2 3 - 1 - - - - - - - - - - - - -	0 serie 500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 15×100 13	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 125/12 21	series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.70 550 0125/12 27	L: 2 L2500 34 1.3 2 138 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77	250 ser 250 ser 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1	ies L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 1.3	20 ser L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9	L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280 60 2.6	
tem Rated thrust Rated current Acceleration thrust Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Length Forcer Width Forcer Weight ap	Unit N A N/A V/m/s Ω mH °C/W mm mm kg/f mm	\$ \$350D 104 1.5 416 6.0 69 23 13.8 21.8 3.5 160 60 1.3 1.00	350 se \$3501 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220 60 1.9 1.00	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2 280 60 2.4 1.00	Q \$42 10 3 40 12 3 12 3 1 2 3 1 2 3 3 1 2 8 3 3 3 1 1 1 1 1 1 1 1	S427 s 270 542 200 15 00 3. 00 600 2.0 12 3 56 1 1' 7 3. 7 1 6 3. 20 31 0 8 0 4. 665 1.6	Series 277 \$42 i0 20 0 3. 10 80 .0 12 0 6 7 22 9 5. 1 11 2 2. 0 40 0 8 2 5. 65 1.6	7Q S43 10 11 0 3.4 10 4.6 .0 12 7 39 2 13 2 2.2 5 7 4 4.1 10 22 0 80 4 3.1 65 1.2	S435 si 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 3.2 0 310 0 800 0 4.2 25 1.2	eries T \$435 5 233 6 233 0 3.0 9 32 0 932 0 12.0 78 26 0 5.2 15 2 2.4 0 400 80 2 5.4 5 1.2 5 2.4	Q \$500 3.8 289 3.8 115 0 15. 76 25 4.4 27 1.5 244 105x 10 105 10	S500 SD S 99 -4 33 - 66 1 2 2 33 - - -	0 serie 500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 05×100 13 1.75	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 125/12 21 1.75	series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.700 5500 125/12 27 1.75	L: 2 L2500 34 1.3 0 138 5.2 27 8.8 8.4 9.2 120 20 50 0.77 2.0	250 ser 250 ser 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0	ies L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 1.3 2.5	20 ser L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5	L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280 60 2.6 2.5	
Item Rated thrust Rated current Acceleration thrust Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Veight ap Pipe outside diameter	Unit N A N/A V/m/s Ω mH °C/W mm mm kg/f mm	\$ \$3500 104 1.5 416 6.0 69 23 13.8 21.8 3.5 160 60 1.3 1.00 35	350 se \$350T 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220 60 1.9 1.00 35	ries \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2 280 60 2.4 1.00 35	Q S42 10 3 40 12 3 12 3 1 2 3 40 22 8 3 1.0 12 4.0 12 1.0 1 2.1 1 4.1 1 4.2 1 4.3 3 1.1 42	S427 s 270 \$42 200 15 00 3. 00 60 2.0 12 3 50 1 11 7 3. 7 1 .6 3. 0 8 0 8 .0 4. .65 1.6	Series 277 \$42 60 20 0 3. 10 80 .0 12 0 6 7 22 9 5. 1 11 2 2. 0 40 0 8 2 5. 35 1.6 .7 42	7Q S43 10 11 0 3.4 10 4.6 .0 12 7 39 2 13 2 2.2 5 7 4 4.4 40 22 0 80 4 3.4 35 1.2 .7 43	S435 state 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 199 7 3.9 111 6 6 3.20 0 3100 0 800 0 4.2 25 1.24 5 43.3	eries ST S4355 5 233 9 3.0 9 932 0 12.1 78 26 9 5.2 15 2.4 0 400 80 2 5.4 5 1.25 43.3	Q \$500 288 3.8 115 0 15. 76 25 4.4 27 1.7 1.7 1.7 1.7 1.7 1.7 5 50 50 50 50 50 50 50 50 50	S500 S00 S 99 4 33 5 66 1 22 2 5 5 5 7 7 7 7 7 7 7 7 00 3 1000 100 100 100 100 100 100	0 serie 500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 15×100 13 1.75 50	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75 50	\$600 \$605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 125/12 21 1.75 60.5	Series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.70 550 125/12 27 1.75 60.5	L: 2 L2500 34 1.3 0 138 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77 2.0 25	250 ser 250 ser 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0 25	L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0 25	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 1.3 2.5 32	20 ser L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5 32	ies L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280 60 2.6 2.5 32	
ttem Rated thrust Rated current Acceleration thrust Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Veight Forcer Weight ap Pipe outside diameter Magnetic pitch (N-N)	Unit N A N/A N/A V/m/s Ω mH °C/W mm mm kg/f mm mm	\$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$	350 se S350T 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220 60 1.9 1.00 35 120	Sister \$3500 190 2.7 760 10.8 70 23 6.9 10.9 2.2 280 60 2.4 1.00 35 120	S42 10 3 40 3 12 3 11 22 8 3.3 1.1 22 8 3.3 1.1 422 1.1 422 1.1	S427 S42 27D S42 00 15 00 60 00 60 2.0 12 3 56 1 1' 7 1 6 3. 20 31 0 80 0 4. 65 1.6 2.7 42 80 18	Series S42 777 S42 00 20 0 3.0 800 800 00 12 00 6 77 22 9 5. 1 11 2 2. 00 400 00 88 2 5. 355 1.6 7.7 42 000 18	70 S43 70 S43 70 11 0 11 0 11 0 3.1 10 46 .0 12 7 39 2 13 2 2.2 5 7 4 4.4 10 22 0 80 4 3.1 35 1.2 .7 43 40 18	State State <th< th=""><th>S4355 S4355 S43555 S4355 S43555 S435555 S435555 S435555</th><th>Q S5000 5 288 3.8 3.8 115 15. 76 255 244 277 105xx 105xx 105xx 105xx 105x 500 5 500 180 180</th><th>S500 S99 33 66 1 22 2 5 5 7 7 7 7 7 7 7 7 7 7 5 5 1 0 5 5 1 0 0</th><th>0 serie 35001 440 5.8 1760 23.2 76 25 3.3 20 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.</th><th>s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75 50 180</th><th>S600 S605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 125/12 21 1.75 60.5 240</th><th>Series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.70 550 125/12 27 1.75 60.5 240</th><th>L250D 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77 2.0 25 90</th><th>250 ser L250T 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0 25 90</th><th>L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0 25 90</th><th>L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 0. 3.2 5 32 120</th><th>20 seri L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5 32 120</th><th>ies L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280 60 2.6 2.5 32 120</th></th<>	S4355 S43555 S4355 S43555 S435555 S435555 S435555	Q S5000 5 288 3.8 3.8 115 15. 76 255 244 277 105xx 105xx 105xx 105xx 105x 500 5 500 180 180	S500 S99 33 66 1 22 2 5 5 7 7 7 7 7 7 7 7 7 7 5 5 1 0 5 5 1 0 0	0 serie 35001 440 5.8 1760 23.2 76 25 3.3 20 1.0 1.0 1.0 1.0 1.0 1.0 1.0 1.	s \$500Q 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75 50 180	S600 S605T 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 125/12 21 1.75 60.5 240	Series \$6050 780 8.4 3100 34.0 93 31 2.2 13 0.70 550 125/12 27 1.75 60.5 240	L250D 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77 2.0 25 90	250 ser L250T 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0 25 90	L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0 25 90	L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 0. 3.2 5 32 120	20 seri L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5 32 120	ies L320Q 109 1.3 436 5.0 87 29 23 28 3.1 280 60 2.6 2.5 32 120	
ttem Rated current Rated current Accelerating current Accelerating current Thrust constant Kf Back electromotive force constant Electric resistance (line) Inductance (line) Thermal resistance Kq Forcer Vlidth Forcer Vlidth Forcer Vlidth ap Pipe outside diameter Magnetic pitch (N-N) Max. manufacturable stroke	Unit N A N/A V/m/s Ω mH °C/W mm mm kg/f mm mm mm	\$3500 104 1.5 416 6.0 69 23 13.8 21.8 3.5 160 60 1.3 1.00 35 120 2120	S350 see S3501 148 1.5 592 6.0 99 33 20.2 33.0 2.4 220 60 1.9 1.00 35 120 2060	ries \$3500 1900 2.7 7600 10.8 700 233 6.9 10.9 2.2 2800 600 2.4 1.000 35 1200 200002	S42 10 3.3 400 3.3 1 2.2 3.3 1.1 2.2 8 3.3 1.1.1 4.2 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1 1.1.1	S427 f S427 f S427 f S422 f S420 f S420 f S420 f	Series S42 777 S42 200 200 3.00 800 800 800 90 5. 11 11 22 2. 00 400 800 800 90 5. 11 11 22 2. 00 400 00 80 55 1.6 55 1.6 1000 18 8000 300	Region Region <th region<<="" th=""><th>S435 ss 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 6 6 3.2 0 310 0 800 0 4.2 25 1.23 43.0 180 80 209</th><th>State State 11 State State 12 State State 13 State State 14 State State 15 State State 16 State State 17 State State 180 State State</th><th>Q S5000 55000 288 3.8.8 3.8.8 115 76 255 25 244 244 105× 105× 105× 105× 105× 105× 105× 105× 105× 105× 105× 100× 105× 100×</th><th>S500 S 0D S 9 - 33 - 66 1 2 2 5 - 7 - 00 - 100 10 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 -</th><th>0 serie 5500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 15×100 13 1.75 50 180</th><th>s 585 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75 50 180 3200</th><th>\$600 \$6057 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 430 125/12 21 1.75 60.5 240 3000</th><th>Series S6050 780 8.4 3100 93 31 2.2 13 0.700 5500 125/12 27 1.75 60.5 240 3000</th><th>L:500 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77 2.0 25 90 3680</th><th>250 series 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0 25 90 3590</th><th>L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0 25 90 3500</th><th>L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 1.3 2.5 32 120 3640</th><th>20 serr L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5 32 120 3580</th><th>ies L3200 109 1.3 436 5.0 87 29 23 280 60 2.6 2.5 32 120 3520</th></th>	<th>S435 ss 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 6 6 3.2 0 310 0 800 0 4.2 25 1.23 43.0 180 80 209</th> <th>State State 11 State State 12 State State 13 State State 14 State State 15 State State 16 State State 17 State State 180 State State</th> <th>Q S5000 55000 288 3.8.8 3.8.8 115 76 255 25 244 244 105× 105× 105× 105× 105× 105× 105× 105× 105× 105× 105× 100× 105× 100×</th> <th>S500 S 0D S 9 - 33 - 66 1 2 2 5 - 7 - 00 - 100 10 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 -</th> <th>0 serie 5500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 15×100 13 1.75 50 180</th> <th>s 585 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75 50 180 3200</th> <th>\$600 \$6057 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 430 125/12 21 1.75 60.5 240 3000</th> <th>Series S6050 780 8.4 3100 93 31 2.2 13 0.700 5500 125/12 27 1.75 60.5 240 3000</th> <th>L:500 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77 2.0 25 90 3680</th> <th>250 series 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0 25 90 3590</th> <th>L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0 25 90 3500</th> <th>L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 1.3 2.5 32 120 3640</th> <th>20 serr L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5 32 120 3580</th> <th>ies L3200 109 1.3 436 5.0 87 29 23 280 60 2.6 2.5 32 120 3520</th>	S435 ss 5D S435 6 175 0 3.0 4 700 0 12.0 9 588 3 19 7 3.9 111 6 6 3.2 0 310 0 800 0 4.2 25 1.23 43.0 180 80 209	State State 11 State State 12 State State 13 State State 14 State State 15 State State 16 State State 17 State State 180 State State	Q S5000 55000 288 3.8.8 3.8.8 115 76 255 25 244 244 105× 105× 105× 105× 105× 105× 105× 105× 105× 105× 105× 100× 105× 100×	S500 S 0D S 9 - 33 - 66 1 2 2 5 - 7 - 00 - 100 10 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 -	0 serie 5500T 440 5.8 1760 23.2 76 25 3.3 20 1.0 330 15×100 13 1.75 50 180	s 585 585 7.7 2340 30.8 76 25 2.2 13 0.8 420 105×100 15 1.75 50 180 3200	\$600 \$6057 610 8.6 2400 34.0 71 24 1.7 10 0.90 430 430 125/12 21 1.75 60.5 240 3000	Series S6050 780 8.4 3100 93 31 2.2 13 0.700 5500 125/12 27 1.75 60.5 240 3000	L:500 34 1.3 5.2 27 8.8 8.4 9.2 7.8 120 20 50 0.77 2.0 25 90 3680	250 series 52 1.3 207 5.2 40 13 13 14 5.2 165 50 1.1 2.0 25 90 3590	L250Q 69 1.3 276 5.2 53 18 17 18 3.9 210 50 1.5 2.0 25 90 3500	L3 L320D 55 1.3 218 5.0 44 15 12 14 6.1 160 60 1.3 2.5 32 120 3640	20 serr L320T 82 1.3 327 5.0 65 22 17 21 4.1 220 60 1.9 2.5 32 120 3580	ies L3200 109 1.3 436 5.0 87 29 23 280 60 2.6 2.5 32 120 3520
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Contact to Nippon Pulse Motor Co. Ltd.

TEL: +81-3-3813-8841 FAX: +81-3-3813-8550 URL: http://www.pulsemotor.com/

for A5L, A5NL, A4AL Linear motor

Serial Compatible Feedback Scale List

	Partner	Series	Resolution* [µm]	Max. rate* [m/s]
		SAP / SVAP / GAP	0.05	2.5
	FAG HAUT MAIL N	LAP	0.1	2
	Magnagagia Ca. Ltd	SR77	0.01 to 1	3.3
	Magnescale Co., Ltd.	SR87	0.01 to 1	3.3
Absolute	Mitutova Comparation	AT573A	0.05	2.5
	Miluloyo Corporation	ST778A(L)	0.1	5
			0.001	0.4
	Renishaw plc	RES LUTE	0.05	20
			0.1	40
	GSI Group Japan Corporation.	M II 5000	0.1 (Variable)	5 (Resolution 0.1 μm)
		SL700 + PL101RP/RHP	0.1	10
Incremental	Magaaaala Ca. Ltd	SL710 + PL101RP/RHP	0.1	10
	magnescale Co., Lla.	SR75	0.01 to 1	3.3
		SR85	0.01 to 1	3.3

* Figures under Resolution and Max. rate indicate values specified for A5 family drives.

These values will be different from those in the feedback scale due to drive max. pulse frequency limit.

Drive and corresponding feedback scale

			Linear mo	tor control	Rotary motor full closed control					
		A5L	A5NL (Note 5)	A4NL	A4AL	A5	A5N (Note 5)	A4N	A4A	
Max. pulse fro	equency	400Mpps	400Mpps	40Mpps	40Mpps	400Mpps	400Mpps	40Mpps	40Mpps	
	ABS	0	0	0	0	0	0	0		
Serial (Note 2)	INC	0	0	(Note 3)	(Note 3)	0	0			
A/B/ phase (Note 4)	INC	0	0		0	0	0		0	

ABS: Absolute INC: Incremental

(Note 1) Resolution and max. velocity of feedback scale are limited by max. pulse frequency.

(Note 2) For A4N, A4NL and A4AL, some feedback scales of serial type cannot be connected. For details. consult us.

(Note 3) Not compatible with A/B/Z phase pulse output from drive.

(Note 4) Max. pulse frequency is 4 Mpps (A/B phase multiplied by 4). When the frequency is more than 4 Mpps, consult us.

(Note 5) Not compatible with Z phase pulse output from drive.



for A5L, A5NL, Feedback so

Linear Encoder

SAP/ AP series/ LAP series/ EXA/EX /EXT series

► Features

• Extremely robust optoelectronic linear encoders.

Connectivity to MINAS series drives.

Great accuracy at high speeds.

Longest absolute measuring length available up to 30 meters.

Enclosed and exposed families available.

Advanced diagnosis tool, via PC connection.



Specification

Item		Description					
Detection system	pto-e linear	pto-electronic absolute linear encoder (Glass)		pto-electronic absolute linear encoder (steel tape)	pto-electronic incremental linear encoder (steel tape exposed)		
Compatible drive	A4/A5			A5L	A5/A5L		
Part No.	SAP	SVAP	AP	LAP	EX-A	EX-	EX-T
Resolution		0.05 µm		0.10 µm	0.	1 µm to 5 µ	m
Max. effective length	1240 mm	2040 mm	3040 mm	30 m	16 m	6 m	30 m
Accuracy (µm/m) 20°C	÷	3 μm / ±5 μ	ım	±5 μm	±10 μm		±5 μm
Max. response speed	2.5 m/s			2 m/s	4 to 8 m/s		
Vibration resistance/ Shock resistance	10 G/ 30 G	20 G/ 30 G	20 G/ 40 G	10 G/ 10 G	20 G/ 100 G		i
Linear coefficient of expansion	(8±	±0.5) × 10 ^{-€}	/°C	(11 0.5) × 10 ⁻⁶ /°C	(11 0.5) × 10 ^{−6} /°C		
Operating temperature/ Storage temperature range				0 to 50°C/ –20 to 70°C			
Operating/storage humidity				20 to 80% RH			
Power supply				5 VDC 10			
Max. current consumption			250 r	nA		150 mA	
Max. cable length			30 r	n		100 m	

Contact to Fagor Automation S. Coop.

 Bo San Andr s No19 E-20500
 Arrasate/Mondrag n, Spain

 TEL: +34-943-719200
 FAX: +34-943-791712
 URL: http://www.fagorautomation.com/





Feedback Scale

MII5000si

Features

Resolution can be multiplied by up to 16384

- Minimal size
- Tape scale compatible (for linear, long axis)
- Glass linear scale compatible (high precision, for X/ /Z axis)
- Glass rotary scale compatible (for θ axis)



Specification

Item	Description				
Sensor si e	H: 11.03 mm L: 38.50 mm W: 13.50 mm				
Power supply	5 VDC 5 @ 172 mA				
Temperature resistance	During operation: 0 to 70°C During storage: -20 to 85°C				
Cable	Double shielding 20 × 10 ⁶ cycles @ 20 mm radius				
Signal period	20μ				
Short-distance accuracy	30 nm with tape scale 20 nm with glass scale				
Long-distance accuracy	±1.5 μm up to 130 mm				

Contact to SI roup apan Corporation. Encoder group

KDX Shibadaimon Bldg. 1F, 2-10-12, Shibadaimon, Minato-ku, Tokyo, 105-0012, Japan TEL: +81-3-6402-9882 FAX: +81-3-6402-9888 URL: http://www.gsig.co. p/microe/index.html

Manufacturer/ Magnescale Magnescale Co. Ltd.

Feedback Magnescale SR70/SR80/SL700 series

Features

- High speed response with Serial interfaces for MINAS series.
- Direct connection with servo drive (Total cost reduction)
- Excellent durability to harsh environment (Dirt, il and Vibration)
- Absolute scales (SR77/SR87) up to 10nm resolution with 200m/min response speed.

Open Type (DI IRULER)	Slim Type Sealed Scale	Robust Type Sealed Scale
SL700 + PL101RP/RHP (A4NL/A5 family) SL710 + PL101RP/RHP (A4NL/A5 family)	SR77 Series (A4/A4N/A4NL/A5 family) SR75 Series (A4NL/A5 family)	SR87 Series (A4/A4N/A4NL/A5 family) SR85 Series (A4NL/A5 family)
	· · · · · · · · · · · · · · · · · · ·	(renezio taniny)

Specification

Item				Descr	ription				
Туре		pen Type (DIGIRULER)		Slim Type S	Sealed Scale	Robust Type Sealed Scale		
Part No.	SL700 PL101RP	SL710 PL101RP	SL700 PL101RHP	SL710 PL101RHP	SR77	SR75	SR87	SR85	
Compatible servo drive		A4NL/A	.5 family		A4/A4N/ A4NL/A5 family	A4NL/A5 family	A4/A4N/ A4NL/A5 family	A4NL/A5 family	
Effective length		50 to 100),000 mm		70 to 2,	040 mm	140 to 3	,040 mm	
Accuracy	±10 Lμm effe * Wh	(integral num ective length i en longer tha	ber in unit of s 3 m or shor an 3 m, consu	1 m when ter) It us.	3+3L/1	3+3L/1,000 μmp-p or 5+5L/1,000 μmp-p * L Effective length (mm)			
Resolution		0.1	μm		A5 family: 0.01 μm to 1 μm A4/A4N/A4NL: 0.05 μm to 1 μm				
Туре		Increr	mental		Absolute	Incremental	Absolute	Incremental	
Response speed		10	m/s			3.3	m/s		
Output signal			Specit	fic to MINAS	series. Serial output				
Origin signal	None	1 point	None	1 point	-	1 point	-	1 point	
Degree of protection	IP50 eq	uivalent	IP67 eq	uivalent	IP54 (wit	hout air purge	e)/IP65 (with	air purge)	

* Nanometer resolution level LASERSCALE is also available (Resolution and maximum response speed depends on drive performance)

* High speed, quick response and high reliability are secured through serial communications.

* Conversion cable CK-T185 is required for A5 connection.

Contact to Magnescale Co. Ltd.

To identify local distributors, please contact Magnescale Co., Ltd. International Sales Division Isehara Headquarters45 Suzukawa, Isehara, Kanagawa 259-1146, JapanURL: http://www.mgscale.com/mgs/language/english/TEL: +81-463-92-7971FAX: +81-463-92-7978E-mail: info-mgs-eng@mgscale.com

. A5NL.

Manufacturer/ Mitutoyo Corporation



Linear Scale

ABS AT500 series/ST700 series

Features

- Encoders of various types, assembly type, separate type, absolute linear support various applications Directly connectable to MINAS series servo drive.
- Provide high resolution and high precision. Assembly configuration is best suited to mechanical processing (AT500 series).
- Electromagnetic induction type is resistant to dirt and its separate construction is best suited to semiconductor and liquid crystal devices (ST700 series).



Specification

Item		Description						
	A	BS AT5000 seri	ies	ABS ST7000 series (compact specification)				
Detection system	Assembly type absolute scale Combined electrostatic capacity and optical ABS linear encoder			Electromagnetic induction type ABS linear encoder				
Part No.	AT573A-SC	AT573A-HC	AT573A-HR/HL	ST778A(L)				
Resolution		0.05 m		0.1 m				
Max. effective length	100 to 2200 mm	100 to 1000 mm	100 to 350 mm	6000 mm (3200 mm and longer: L series)				
Detection head si e (mm)				50 × 28 × 11				
Accuracy (µm): 20°C	3 + 3 Lo/1000 2 + 2Lo/1000			5 + 5Lo/1000				
Max. response rate	2. 5m/s			5 m/s				
Vibration resistance/shock resistance	20G/35G	15G	/20G					
Linear expansivity	8)	6.5±0.5) × 10 ⁻⁶ /	O	(12 1.5) ×10 ⁻⁶ /°C				
Operating temperature/ storage temperature range	0 to	45 °C/–20 to 7	0 °C	0 to 50 °C/–20 to 70 °C				
Operating humidity/ storage humidity range			20 to 80%RH	I (No dewing)				
Power supply		5 VDC 5		5 VDC 10 (Ripple + spike noise components should be 100 mV or below.)				
Max. current consumption			270 m/	A (MAX)				
Head cable length	2 m (Detect	ion head to inte	erface B X)	1 m				
Signal cable length		3 m						
Max. cable length		29	m (Including ler	ngth of head cable)				
Detection head mount				1 on the top and 1 on one side				

Contact to Mitutoyo Corporation

20-1, Sakado 1-Chome, Takatsu-ku, Kawasaki-shi, Kanagawa 213-8533, Japan TEL: +81-44-813-8234 URL: http://www.mitutoyo.co. p/eng/corporate/network/overseas/index.html

Optical Absolute Linear Encoder RESOLUTE^{**} series

Features

- True absolute encoder
- Resolution (velocity) : 0.1 µm (40 m/s)
 - : 50 nm (20 m/s)
- Determines absolute position upon power up
- Range of scales for a variety of applications
 - Low SDE for smooth velocity control
 - Worldwide subsidiary support network
- Unique single-track scale eliminates yaw de-phasing problems

:1 nm (0.4 m/s)



Specification

Series	RESOLUTE" RELA	RESOLUTE" RSLA	RESOLUTE " FASTRACK/RTLA	RESOLUTE" RTLA-S			
Feature	Fine precision and low thermal expansion	The world s most accurate long-length scales	Quick and easy scale replacement	Easiest installation			
Scale material	Invar	Stainless steel	Stainless steel tape	Stainless steel tape			
Thermal expansion coefficient	0.4 ppm/°C	10.8 ppm/°C	10.6 ppm/°C	10.6 ppm/°C			
Scale accuracy	±1 μm	±1.5 μm/m	±5 μm/m	±5 μm/m			
Scale length	80 to 1,130mm	80 to 5,000mm	100 to 10,000mm	100 to 5,000mm			
Scale mounting options	Bonding or Clip/Clamp	Bonding or Clip/Clamp	Track (carrier) mounting	Self-adhesive			
Read head sie HLW	18 × 36 × 16.5 mm						
Scale si e H W	1.5 × 15 mm	1.5 × 15 mm	0.4 × 18 mm	0.2 × 8 mm			

Contact to Renishaw plc

New Mills Wotton-under-Edge Gloucestershire GL12 8JR, United Kingdom URL: www.renishaw.com TEL: +44-1453-524524

E-mail: international@renishaw.com

-, A5NL,





AC Servo Actuator SHA-P Series SHA25P/SHA32P

Features

- The AC servo actuator incorporates the precise control speed reducer (Harmonic Drive R) to the flat AC servo motor.
- The design of the actuator is flat and has hollow shaft structure. Piping, wiring, laser light, etc., can be passed through the through-hole in the center.
- Excellent one way positioning accuracy : 50 sec (0.83) with reduction ratio 1/51, and 40 sec (0.67) with reduction 1/81 or higher ratio.
- Torque-volume ratio is 5 times or more that of direct drive motor.



Specification

Model					SHA25P			SHA32P						
Item			51	81	101	121	161	51	81	101	121	161		
Associated drive				М	CDHT35	20		MDDHT3530						
Max. torque "2		Nm	127	178	204	217	229	277	395	433	459	484		
Allowable continuous torque ^{*2 *3}		Nm	41	67	81	81	81	92	153	178	178	178		
Max. revolution speed		r/min	109.8	69.1	55.4	46.3	34.8	94.1	59.3	47.5	39.7	29.8		
Max. current "2		А	8.6	7.5	7.0	6.3	5.2	17.1	15.2	13.5	12.2	9.9		
Allowable continuous current ^{*2 *3}		A	3.0	3.0	2.9	2.6	2.1	6.0	6.0	5.7	5.0	4.1		
Moment of Inertia	D²/4	kg∙m²	0.56	1.42	2.2	3.2	5.6	2.0	5.1	8.0	11.0	20.0		
Reduction ratio			1:51	1:81	1:101	1∶121	1∶161	1:51	1:81	1:101	1∶121	1∶161		
Allowable moment load Nm					258			580						
Moment rigidity Nm/rad					39.2×104			100×104						
One way positioning accuracy		sec	50	40	40	40	40	50	40	40	40	40		
Encoder			Magnetic absolute encoder											
Output resolution		Pulses/ Rev.	6,684,672	10,616,832	13,238,272	15,859,712	21,102,592	6,684,672	10,616,832	13,238,272	15,859,712	21,102,592		
Mass (without brake) kg					2.95			5.9						
Mass (with brake) kg					3.1			6.2						
Mounting direction			Can be installed in any direction.											

*1: Values in the table above represent typical values at output shaft.

*2: Typical values obtained when standard drives are used (driving with ideal sine wave).

*3: Values obtained at temperature rise saturated with the actuator mounted on the aluminum heatsink shown below. SHA25P: 350 × 350 × 18 mm SHA32P: 400 × 400 × 20 mm

Contact to Harmonic Drive Systems Inc. Overseas Division

1856-1 Hotakamaki, Azumino-shi, Nagano, 399-8305, Japan TEL: +81-263-83-6935 FAX: +81-263-83-6518 URL: http://www.hds.co. p/



AC Servo Actuator SHA-P Series SHA40P/SHA58P/SHA65P

Features



Max. torque mapping



for A5, A5N

Specification

M		Model		\$	SHA40	2		SHA58P				SHA65P			
			51	81	101	121	161	81	101	121	161	81	101	121	161
Associated drive			MDDHT5540					MFDHTA3 0				MFDHTB3A2			
Max. torque *2 Nm		523	675	738	802	841	1924	2067	2236	2392	2743	2990	3263	3419	
Allowable continuous torque ^{12 13} Nm		160	263	330	382	382	714	905	969	969	921	1149	1236	1236	
Max. revolution speed r/min		r/min	78.4	49.4	39.6	33.1	24.8	37.0	29.7	24.8	18.6	34.6	27.7	23.1	17.4
Max. current ^{*2} A		26.7	21.8	19.4	17.9	14.6	45.0	39.0	36.0	30.0	62.0	55.0	51.0	41.0	
Allowable continuous current *2 *3		A	9.0	9.0	9.0	8.8	7.2	17.7	17.8	16.4	13.4	22.0	21.9	20.1	16.3
Moment of Inertia	D²/4	kg∙m²	5	13	20	28	50	96	149	214	379	110	171	245	433
Reduction ratio		1:51	1:81	1:101	1:121	1:161	1:81	1:101	1:121	1:161	1:81	1:101	1:121	1:161	
Allowable moment load Nm		849					2180				2740				
Moment rigidity Nm/rad		179 × 104					531 × 104				741 × 10 ⁴				
One way positioning accuracy Sec		sec	50	40	40	40	40	40	40	40	40	40	40	40	40
Encoder			Magnetic absolute encoder												
Output resolution Pulses Rev.		Pulses/ Rev.	6,684,672	10,616,832	13,238,272	15,859,712	21,102,592	10,616,832	13,238,272	15,859,712	21,102,592	10,616,832	13,238,272	15,859,712	21,102,592
Mass (without brake) kg		9.9					29.5				37.5				
Mass (with brake) kg		10.7					32 40								
Mounting direction			Can be installed in any direction.												

*1: Values in the table above represent typical values at output shaft.

*2: Typical values obtained when standard drives are used (driving with ideal sine wave).

*3: Values obtained at temperature rise saturated with the actuator mounted on the aluminum heatsink of 650 × 650 × 30 mm.

Contact to Harmonic Drive Systems Inc. Overseas Division

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http://www.gsig.co. p/microe/index.html

http://www.hds.co.p/

http://www.hptec.co. p/

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HI-P Tech Corporation Sales Dept.

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http://www.pulsemotor.com/

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InterMotion - Special site: http://www.intermotion.p

Prime Motion Inc.

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Cautions for Proper Use

· Practical considerations for exporting the product or assembly containing the product When the end user of the product or end use of the product is associated with military affair or weapon, its export may be controlled by the Foreign Exchange and Foreign Trade Control Law. Complete review of the product to be exported and export formalities should be practiced. . This product is intended to be used with a general industrial product, but not designed or manufactured to be used in a machine or system that may cause personal death when it is failed. • Installation, wiring, operation, maintenance, etc., of the equipment should be done by gualified and experienced personnel. · Apply adequate tightening torque to the product mounting screw by taking into consideration strength of the screw and the characteristics of material to which the product is installed. vertightening can damage the screw and/or material undertightening can result in loosening. Example) Steel screw (M5) into steel section: 2.7-3.3 N m. · Install a safety equipments or apparatus in your application, when a serious accident or loss of property is expected due to the failure of this product. · Consult us if the application of this product is under such special conditions and environments as nuclear energy control, aerospace, transportation, medical equipment, various safety equipments or equipments which require a lesser air contamination. • We have been making the best effort to ensure the highest quality of the products, however, application of exceptionally larger external noise disturbance and static electricity, or failure in input power, wiring and components may result in unexpected action. It is highly recommended that you make a fail-safe design and secure the safety in the operative range. • If the motor shaft is not electrically grounded, it may cause an electrolytic corrosion to the bearing, depending on the condition of the machine and its mounting environment, and may result in the bearing noise. Checking and verification by customer is required · Failure of this product depending on its content, may generate smoke of about one cigarette. Take this into consideration when the application of the machine is clean room related. · Please be careful when using in an environment with high concentrations of sulfur or sulfric gases, as sulfuration can lead to disconnection from the chip resistor or a poor contact connection. • Take care to avoid inputting a supply voltage which significantly exceeds the rated range to the power supply of this product. Failure to heed this caution may result in damage to the internal parts, causing smoking and/or a fire and other trouble. • The user is responsible for matching between machine and components in terms of configuration, dimensions, life expectancy, characteristics, when installing the machine or changing specification of the machine. The user is also responsible for complying with applicable laws and regulations. • The product will not be guaranteed when it is used outside its specification limits. · Parts are subject to minor change to improve performance. Read and observe the instruction manual without fail for proper usage of the products. Consult to the dealer from whom you have purchased this product for details of repair work. Repair When the product is incorporated to the machine you have purchased, consult to the machine manufacturer or its dealer. Electric data of this product (Instruction Manual, CAD data) can be download from the following web site URL http://industrial.panasonic.com/ww/i e/25000/motor fa e/motor fa e.html Contact to : Panasonic Corporation, Appliances Company, Motor Business Unit

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to the products as of Jan 1, 2012.





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